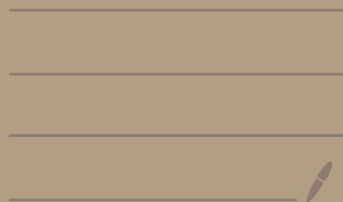


CS 294



CSPs

V : set of variables

D : constant size domain $\rightarrow$ w.r.t. size of the input

Local Constraints (constant # of variables / constraint)

Questions in CSP

Satisfiability: For an input I , $\exists$ a satisfying assignment?

$\hookrightarrow$ Dichotomy Theorem [91~18]

Approximability: find an assignment satisfying max # constraints

$\hookrightarrow$ PCP Theorem [91~92] $\rightarrow$ Unique Games Conjecture

$\hookrightarrow$ Satisfiable Instances, Promise CSPs

Counting: find the # of satisfying solutions

Random CSP: Average case analysis

$\hookrightarrow$ Structural Questions: 1) $\Pr[I \text{ is satisfiable}] = 1$ or 0 ?

$\hookrightarrow$ Solution Space: 1) # of solutions 2) Geometry of solutions

$\hookrightarrow$ Algorithmic Questions: How to solve a random input algorithmically?

Quantum CSPs: Local Hamiltonians

Meta-Questions: $2SAT \in P$, but $3SAT \in NPComplete$. Why?

↳ This is usually hard, but CSP has a good explainable theory!

⇒ Given a description of a CSP Γ , is $\Gamma \in P$ or $\Gamma \in NPC$?

⇒ What is the best approximation ratio for Γ ?

Satisfiability

Def) CSP: A CSP Γ is specified by:

1) Constant sized domain D

2) Finite set of relations $\{R_1, \dots, R_k\}$ over the domain

ex) $D = \{0, 1\}$. $R_1 = \{(0,0), (0,1), (1,0)\}$. $R_2 = \{(0,0), (1,1), (1,0)\}$.

$R_3 = \{(0,0), (0,1), (1,1)\}$. $R_4 = \{(0,1), (1,0), (1,1)\}$

An instance of CSP Γ is: Variables $V = \{V_1, \dots, V_n\}$. Constraints $C_1, \dots, C_m$, where each $C_i \equiv$ some R_i applied to a subset of V .

ex) Γ has a relation R which is binary & symmetric. $R \subseteq D^2$

↳ R is a graph H : Instance of $\Gamma \iff$ Graph G on n vertices

$CSP(\Gamma_H): \exists$ a map $f: G \rightarrow H$ s.t. $\forall (u,v) \in G, (f(u), f(v)) \in H$.

$H = \triangle \rightarrow$ this corresponds to 3-Coloring! What about

$H = \square$ (in P) or $H = \text{pentagon}$ (in NPC)?

[Hell - Nesteril]: $\Pi_H \in P$ if H is bipartite, $\in NPC$ otherwise.

Schaefer's Theorem: Among all Boolean CSPs, following are in P :

1) 2-SAT 2) Horn-SAT 3) Dual Horn SAT 4) Lin Eq. 5) Trivial CSP

And the rest are in NPC . $\hookrightarrow$ all variables are negated

[Feder - Vardy]: Every CSP is in P or NP -Complete. (Conjecture)

Poly morphisms

ex) Linear Equations: $[A][x] = [b]$ over $\mathbb{Z}_2$.

Suppose we have 3 solutions to the linear systems, $Ax = Ay = Az = b$.

Consider $A(x+y-z) = b$. $(x+y-z)$ is also a solution.

Polymorphisms combine solutions of a CSP to produce another solution.

Concretely, $h: \mathbb{Z}_2^3 \rightarrow \mathbb{Z}_2$, $h(a,b,c) = a - b + c \pmod{2}$ is a polymorphism

for LINEQ since $\forall Ax = b$, $\forall x,y,z$ solutions of the following produces

$x = [x^{(1)}, x^{(2)}, \dots, x^{(n)}]$ a new solution $w = h(x,y,z)$.

$y = [y^{(1)}, y^{(2)}, \dots, y^{(n)}]$

$z = [z^{(1)}, z^{(2)}, \dots, z^{(n)}]$

$w = x+y-z = [x^{(1)}+y^{(1)}-z^{(1)}, \dots, x^{(n)}+y^{(n)}-z^{(n)}]$

Some polymorphisms: 2-SAT $\rightarrow$ Maj(a,b,c), HORN-SAT $\rightarrow$ AND(a,b),
 Dual HORN-SAT $\rightarrow$ OR(a,b), LINEQ $\rightarrow$ a+b-c, Trivial CSP $\rightarrow$ any h.

ex) $x \xrightarrow{x \Rightarrow y} y \xrightarrow{\bar{y} \Rightarrow z} z \xrightarrow{\bar{z} \Rightarrow \bar{w}} w$

(For 2-SAT) $\xrightarrow{\bar{y} \Rightarrow \bar{w}}$

x	y	z	w
0	0	0	0
0	0	0	1
0	0	1	0
0	0	1	1
0	1	0	0
0	1	0	1
0	1	1	0
0	1	1	1
1	0	0	0
1	0	0	1
1	0	1	0
1	0	1	1
1	1	0	0
1	1	0	1
1	1	1	0
1	1	1	1

Maj(x,y,z) 0 0 1 1 0 0 1 1 0 0 1 1 0 0 1 1

Every CSP has a trivial polymorphism: $h(a,b,c) := b$ (dictator function)

"Algebraic" Dichotomy: CSP $\Gamma \in P$ iff it has a nontrivial polymorphism. (otherwise $\Gamma \in NPC$)

$\hookrightarrow$ We can recursively combine h for more polymorphisms! (universal algebra*)

ex) $\text{Maj}(a,b,c) \rightarrow \text{Maj}(a,b,\text{Maj}(c,d,e))$

$\leftarrow \text{Maj} \xrightarrow{a} \text{Maj} \xrightarrow{e} \text{Maj}$

[Hardness]: no nontrivial polymorphism if $\Gamma \in NPC$. (03 ~ 04)

[Algorithm]: nontrivial polymorphism of Γ implies $\Gamma \in P$. (18 ~ 19)

Theorem) CSP Γ_1 reduces to CSP Γ_2 iff $\text{Poly}(\Gamma_2) \subseteq \text{Poly}(\Gamma_1)$.

Polymorphisms as Solution to CSP (WLOG, 3-SAT): Consider $\text{Poly}^{(3)}(3\text{-SAT})$, a polymorphism on 3 bits of 3-SAT candidates.

0	0	0	0	1	1	1	1	$\rightarrow h_1(x) = x_1$
0	0	1	1	0	0	1	1	$\rightarrow h_2(x) = x_2$
0	1	0	1	0	1	0	1	$\rightarrow h_3(x) = x_3$

$$h(0,0,0) \quad h(0,0,1) \quad \dots \quad h(1,1,1) \quad \text{where } h(a,b,c): \{0,1\}^3 \rightarrow \{0,1\}$$

$$X_{000} \quad X_{001} \quad \dots \quad X_{111}$$

$\text{DICT}_{3\text{SAT}}^{(3)} := (\text{Variables} := \{X_{000}, \dots, X_{111}\}, \rightarrow 8 \text{ variables})$

$\text{Constraints} := \{\text{every constraint satisfied by the dictator function}\}$.

$\hookrightarrow$ any assignment on $\text{DICT}_{3\text{SAT}}^{(3)}$ is a function on 3 bits.

Claim: any satisfying assignment for $\text{DICT}_{3\text{SAT}}^{(3)}$ is a polymorphism for 3SAT.

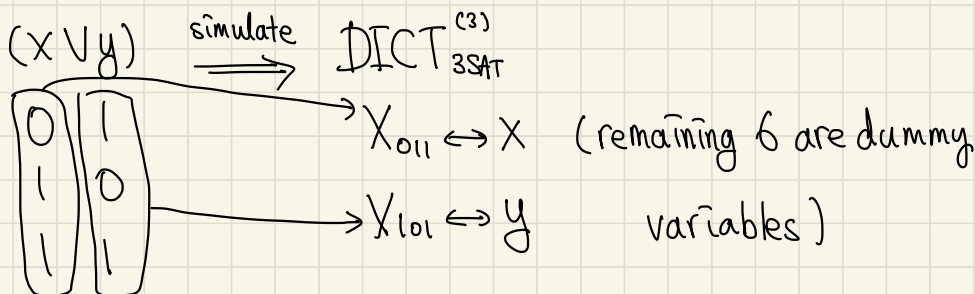
Generally, $\forall \Gamma, \forall k$, a satisfying assignment of $\text{DICT}_{\Gamma}^{(k)}$ is a k -bit poly. of Γ .

Def) Dictatorship Gadget: $\text{DICT}_{\Gamma}^{(k)}$ for all Γ and arity k .

$\text{DICT}_{3\text{SAT}}^{(3)} :=$ instance of 3SAT on 8 variables.

$\hookrightarrow$ 3SAT has no nontrivial poly. $\Leftrightarrow$ the only satisfying assignment to $\text{DICT}_{3\text{SAT}}^{(3)}$ are $h_1(X_1, X_2, X_3) = X_1, \dots, h_8(X_1, X_2, X_3) = X_3$ (dictatorships)

If we were to reduce 2SAT $\rightarrow$ 3SAT:



Generally, if Γ has k satisfying conditions, reduce it to $\text{DICT}_{\Gamma}^{(k)}$.

Then, $\text{DICT}_{\Gamma}^{(k)}$ proves hardness iff we cannot "add more rows" to it.

Algorithms for CSP: Suppose $\text{Poly}(\Gamma)$ is nontrivial. Then $\Gamma \in P$.

↳ Two big ideas: 1) Local Propagation 2) Gaussian Elimination over $\mathbb{F}_p$.

Local Propagation: Consider a 2SAT instance, $\bar{z} \wedge (\bar{x} \vee w) \wedge (\bar{x} \wedge y)$.

Look at local states and eliminate infeasible options. After it stops,

◦ $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$ there are sets of plausible local states.

◦ $\begin{pmatrix} y \\ z \end{pmatrix}$ A width k -local prop. $\rightarrow \forall k$ -tuples $S \subseteq V$,

$\begin{pmatrix} z \end{pmatrix}$ $\begin{pmatrix} x \end{pmatrix}$ $\exists$ a set of partial assignments $A_S \subseteq \{0, 1\}^{|S|}$.

◦ $\begin{pmatrix} w \end{pmatrix}$ $\begin{pmatrix} x \end{pmatrix}$ $\hookrightarrow$ partial assignments A_S are consistent $\Rightarrow TCS$,

A_T is consistent with A_S if every assignment $\sigma_T \in A_T$ can be extended to an assignment in A_S .

Def) A CSP Γ is width k if a width k -local prop. decides Γ .

* LINEQ is not bounded-width! (Intuitively, local conditions do not imply anything about the system as a whole)

* Local prop. can be simulated by LP, i.e. LPs that execute local prop.

↳ Variables: $P_{S,\alpha}$ for $S \subseteq V$, $\alpha \in \{0, 1\}^{|S|}$ where $P_{S,\alpha} := \mathbb{1}\{S \text{ is in state } \alpha\}$

Constraints: $(S \text{ is assigned some } \alpha) \sum_{\alpha} P_{S,\alpha} = 1$.

(extension consistency of S) $P_{S \cup \{i\}, \alpha_0} + P_{S \cup \{i\}, \alpha_1} = P_{S, \alpha}$

(violation of S) $P_{S, \alpha} = 0$ if α violates a constraint of CSP for S .

* Gaussian Elimination is not captured by LP/Convex Optimization!

↳ However, a general algorithm for CSP must involve both LP & GE!

Randomized Algorithm for LINEQ on $\mathbb{F}_2$: start with $O(n^2)$ random inputs.

Delete any candidates inconsistent with the first constraint's parity.

Then, produce $O(n^{3/2})$ inputs via polymorphism. Repeat over constraints.

Probabilistic Checkable Proofs

Def) Proof System: A verifier $(\text{Claim}, \text{Proof}) \rightarrow \overset{\text{accept/reject}}{\{0,1\}} \in \mathcal{P}$

Completeness: True claims have proof (if $\text{Claim} = \text{True}$, $\exists \text{proof s.t. } v[c,p] = 1$)

Soundness: False claims have no proof (if $\text{Claim} = \text{False}$, $\forall \text{proof } v[c,p] = 0$)

↳ If we make the verifier probabilistic, we constrain on $\Pr[v[c,p] = 0/1] \geq 2/3$.

PCP: verifier is probabilistic and it reads only $O(1)$ bits of proof!

Def) $\text{PCP}(q, L)$: $q := \#$ of queries into proof, $L :=$ length of proof

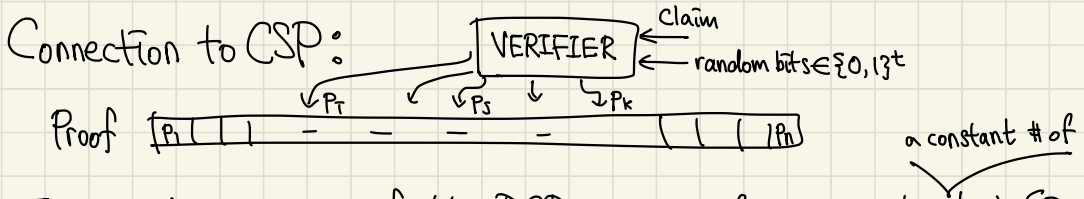
Naïve PCP for 3SAT: Claim: ϕ is satisfiable, Proof: $x \in \{0,1\}^n$.

↳ Verifier: Picks a random clause C from ϕ , checks if C is satisfied.

⇒ Completeness is evident, 1.

⇒ Soundness: ϕ is not satisfiable, then $\forall x, \exists c$ s.t. x violates C .

$$\hookrightarrow \Pr[\text{verifier rejects } x] \geq \frac{1}{\# \text{ clauses}} = O\left(\frac{1}{\text{poly}(n)}\right) //$$



For a single execution of the PCP, the verifier expects bits $\{p_1, \dots, p_k\}$ to satisfy a certain constraint on those bits.

The set of all possible executions gives a set of constraints on local bits. $\Rightarrow$ CSP instance I_v .

$$\max_{\text{proof } p} \{ \Pr[V[C, p]] \} \Leftrightarrow \max_{p \sim \text{assignment of proof bits}} \{ \text{val}(I_v, p) \}$$

fraction of constraints of I_v satisfied by p

Theorem) PCP Theorem [91]: $NP = PCP(\Theta(1), \text{poly}(n))$

Relevance: Proofs ("Computation") are brittle objects, i.e. one false claim in a proof can break the entire proof. Then, it's surprising that we can check a proof's validity with only constant # of samples!

Exponential Sized PCP for NP

Claim: $NP \subseteq PCP(30, 2^{n^2})$.

The NPC problem: QUAD-EQ.

Variables: $x_1, \dots, x_n \in \{0, 1\} = \mathbb{F}_2$. $\rightarrow$ ex) $x_1 x_2 - x_3 = 0$

Constraints: quadratic equations each on 3 variables.

Goal: Is there a satisfying assignment (decision problem)

Proof of $QUAD-EQ \in NP$: $CIRCUIT-SAT \leq_p QUAD-EQ$.

Consider a CIRCUIT-SAT with NOT and AND gates. Variables will

be all wires in the circuit, $w_1, \dots, w_n$. For all $\frac{w_i}{w_j} \xrightarrow{\text{AND}} \frac{w_k}{w_l}$, $w_i w_j = w_k$.

For all $\frac{w_i}{w_j} \xrightarrow{\text{NOT}} \frac{w_l}{w_m}$, $w_i = 1 - w_j$. The output $w_n = 1$. Reduction is complete. //

Hadamard Codes (Truth table of linear function)

$\hookrightarrow \text{Encode}(l_1, \dots, l_n) \Rightarrow \text{Table of linear function } L(x) = \langle l, x \rangle = \sum_i l_i x_i$

$\Rightarrow$ In effect, we encode n bits into 2^n bits $(0, l_1, l_2, l_3, l_1 + l_2, \dots)$

Self-Correction: Suppose $\tilde{L}: \mathbb{F}_2^n \rightarrow \mathbb{F}_2$ that is ε -close to a linear function (Hadamard code) L . $\Pr[x \in \mathbb{F}_2^n, L(x) = \tilde{L}(x)] \geq 1 - \varepsilon$.

$\forall x \in \mathbb{F}_2^n$, we want $L(x)$ from $\tilde{L}(x)$. Consider $\tilde{L}(x+y) - \tilde{L}(y)$.

* A true linear function L would yield $L(x+y) - L(y) = L(x)$.

Claim: $\Pr[\tilde{L}(x+y) - \tilde{L}(y) = L(x)] \geq 1 - 2\varepsilon$ for a random $y \sim \mathbb{F}_2^n$.

Proof: Fix x . When y is random, $x+y$ is uniformly random over $\mathbb{F}_2^n$.

$$\hookrightarrow \Pr[\underbrace{\tilde{L}(x+y) = L(x+y)}_{e_1}] \geq 1 - \varepsilon, \Pr[\underbrace{\tilde{L}(y) = L(y)}_{e_2}] \geq 1 - \varepsilon.$$

$\Rightarrow$ By union bound, $\Pr[e_1 \wedge e_2] \geq 1 - 2\varepsilon$. //

Theorem) Linearity Testing^{*(later)}: Suppose $\tilde{L}: \mathbb{F}_2^n \rightarrow \mathbb{F}_2$ satisfies

$$\Pr_{x,y}[\tilde{L}(x+y) = \tilde{L}(x) + \tilde{L}(y)] \geq 1 - \varepsilon, \text{ then } \exists \text{ a linear function } L$$
$$\text{s.t. } \Pr_x[\tilde{L}(x) = L(x)] \geq 1 - \varepsilon.$$

Intuition: To test linearity, sample $x, y \sim \mathbb{F}_2^n$. Test whether

$$\tilde{L}(x) + \tilde{L}(y) = \tilde{L}(x+y) \quad (\text{Linearity test is sound})$$

A Testing Problem: $\vec{l} = (l_1, \dots, l_n) \in \mathbb{F}_2^n$. Test if $\vec{l} = \vec{0}$?

Suppose we have access to $L(x) = \langle \vec{l}, x \rangle$. Then, check $L(x) = 0$ for a random $x \in \mathbb{F}_2^n$.

Claim: Suppose $\vec{l} \neq \vec{0}$. $\Pr_x[L(x) = \langle \vec{l}, x \rangle = 0] \geq 1/2$. (Exercise)

Construction of PCP for QUAD-EQ: Variables $l_1 \dots l_n \in \mathbb{F}_2$.

Quadratic equations $q_i(l) = 0$ for $i = 1 \dots m$. Suppose l satisfies.

PCP Proof: $L(x) := \langle l, x \rangle$ (Hadamard encoding of l)

$$\hookrightarrow L(x): \overbrace{\hspace{10em}}^{2^n}$$

$H(x): \mathbb{F}_2^{n^2} \rightarrow \mathbb{F}_2$, $H(x) :=$ Hadamard encoding of $l^{\otimes 2} = \{l_i l_j \mid i, j \in [n]\}$ $\rightarrow |l^{\otimes 2}| = n^2$

$$\hookrightarrow H(x): \overbrace{\hspace{10em}}^{2^{n^2}}$$

$$\hookrightarrow H(CC_{ij}) = \sum_{i,j} C_{ij} l_i l_j = \langle C, l^{\otimes 2} \rangle$$

Verifier: Suppose the prover gives $\tilde{L}(x)$ and $\tilde{H}(x)$. First, test $\tilde{L}$

is ε -close to a linear function using 3 bits in linear time. Next test

$\tilde{H}$ is ε -close to a linear function $\hat{H}(c) = \sum_{i,j} M_{ij} C_{ij}$ (3 bits). If these

are not ε -close, we will reject with probability ε . Now, we can

pretend we have access to L and $\hat{H}$ via self-correction. We test

if $M_{ij} = l_i l_j \forall i, j$ (linear to quadratic consistency). If so, we are

convinced we have access to true L and H . The goal is to test

whether $q_i(l) = 0$ for all $q_1, \dots, q_m$. Pick $r_1, \dots, r_m \in \mathbb{F}_2^m$. Let $R(l) :=$

$\sum_i r_i q_i(l)$. Test if $R(l) = \sum_{i,j} r_{ij} l_i l_j + \sum_i s_i l_i + b = 0$. This is easy

since we can rewrite $R(l) = H(r_{ij}) + L(s) + b$. We recover

$H(r_{ij})$ and $L(s)$ each with 2 bits of $\tilde{H}$ and $\tilde{L}$. Then, R gives a

possible violation of l based on $r_1, \dots, r_m$. //

Linearity Testing

Input: $f: \mathbb{F}_2^n \rightarrow \mathbb{F}_2$, want to test if f is close to linear.

→ Pick $x, y \in \mathbb{F}_2^n$ u.a.r. Check $f(x+y) = f(x) + f(y)$. [BLR]
Blum-Luby-Rubinfeld

Thm) $\forall$ function f , $\exists$ a linear function g s.t. $\text{dist}(f, g) = \Pr_n[f(n) \neq g(n)]$
 $\leq \frac{1}{2} \underbrace{\Pr[\text{BLR rejects } f]}_{\hookrightarrow \delta}$. ($\frac{1}{2}$ can be removed if done with Fourier)

$\mathbb{F}_2$ Facts:

1) $+1 = -1 \pmod{2} \rightarrow x+y = x-y$, $x+y+y = x$.

2) fix $x \in \mathbb{F}_2^n$. $y \sim \mathbb{F}_2^n$ u.a.r. $\Rightarrow x+y \sim$ u.a.r. $\mathbb{F}_2^n$.

3) fix $v \neq 0$, $\Pr_x[\langle v, x \rangle \neq 0] = \frac{1}{2}$.

Reminder) $f(x) = f(x+z) - f(z)$ if f is linear.

Define $g(x) := \max_{z \in \mathbb{F}_2^n} (f(x+z) - f(z))$.

Claim A: g is a linear function if $\delta < \frac{1}{20}$. → $\Pr[\text{BLR rejects } f]$

Claim B: $\text{dist}(f, g) = \Pr_x[f(x) \neq g(x)] \leq 2\delta$.

Let $P_x := \Pr_y[g(x) = f(x+y) - f(y)] \forall x$.

"Surprising" Claim: $\forall x, P_x \geq 1 - 2\delta$.

Proof: Consider $\Pr_{y,z}[\overbrace{f(x+y) - f(y) = f(x+z) - f(z)}^A]$ for a fixed x . assume $g(x) = 0$.

$\hookrightarrow f(x+y) - f(y)$ is a bit with bias $P_x \Rightarrow \Pr[A] = P_x P_x + (1 - P_x)(1 - P_x) = P_x^2 + (1 - P_x)^2$.

Now, consider event $A: f(x+y) - f(y) = f(x+z) - f(z)$

$\Leftrightarrow f(x+y) + f(x+z) = f(y) + f(z)$ (we can ignore $\pm$)

$\rightarrow \Pr[A] = \Pr_{y,z}[f(x+y) + f(x+z) = f(y) + f(z)]$.

$\hookrightarrow f(y) + f(z) = f(y+z)$ with probability $(1 - \delta)$.

$\hookrightarrow f(x+y) + f(x+z) = f(x+y+x+z) = f(y+z)$ with prob. $(1 - \delta)$.

$\Rightarrow \Pr[A] \geq 1 - 2\delta \Rightarrow P_x^2 + (1 - P_x)^2 = \Pr[A] \geq 1 - 2\delta$.

$\Rightarrow \delta \geq \underbrace{P_x(1 - P_x)}_{P_x \geq \frac{1}{2}} \geq \underbrace{\frac{1}{2}(1 - P_x)}_{\frac{1}{2}} \Rightarrow \underline{P_x \geq 1 - 2\delta} //$

Proof of Claim A: Need to prove $g(x) + g(y) = g(x+y) \forall x, y$.

$g(x) \oplus f(x+z) - f(z)$ with prob. $1 - 2\delta$. (due to surprising claim)

$+ \overbrace{g(y) \oplus f(y+w) - f(w)}^{(11)}$ //

$g(x+y) \oplus \underbrace{f(x+y+z+w) - f(z+w)}_{\substack{\text{w.p. } 1-\delta \quad \text{w.p. } 1-\delta}}^{(11)}$ //

(witness)
one instance is enough.

$\rightarrow$ w.p. $1 - 8\delta$ over $z \& w$, all $\oplus$ happens $\Rightarrow \exists z, w$ s.t. this happens.

$\hookrightarrow 1 - 8\delta > 0 \Rightarrow \delta < \frac{1}{8}$

$\Rightarrow g(x+y) = g(x) + g(y)$.

Proof of Claim B: $\Pr_{x,y}[f(x)+f(y) \neq f(x+y)] = \delta$ (def. of BLR)

$$\Leftrightarrow \Pr_{x,y}[f(x) \neq f(x+y) - f(y)] = \delta.$$

Let $\text{Bad} := \{x \mid f(x) \neq \underbrace{g(x)}_{\text{Maj}_y(f(x+y)-f(y))}\}$. $\Pr[f(x) \neq f(x+y) - f(y) \mid x \in \text{Bad}] \geq 1/2$.

$$\Pr[f(x)+f(y) \neq f(x+y)] \geq \Pr[x \in \text{Bad}] \cdot \boxed{} \geq \frac{1}{2} \cdot \Pr[x \in \text{Bad}]$$

$$\Rightarrow \Pr[x \in \text{Bad}] \leq 2 \cdot \Pr[f(x)+f(y) \neq f(x+y)] = 2\delta. //$$

Exp. PCP with Linearity Testing: When testing $\tilde{L}$ and $\tilde{H}$, use BLR to test if they are ε -close to a linear function. Each rejects with prob. $\Omega(\varepsilon)$, and if not, $\exists$ linear functions L and H s.t.

$\text{dist}(\tilde{L}, L) \leq \varepsilon$ and $\text{dist}(\tilde{H}, H) \leq \varepsilon$. Then, pick $x, y \in \mathbb{F}_2^n$ u.a.r.

$$\text{Test } (\sum l_i x_i)(\sum l_j y_j) = \underline{L(x) \cdot L(y)} = H(xy^T) = \sum H_{ij} x_i y_j = \sum h_i l_j x_i y_j.$$

More $\mathbb{F}_2$ Facts:

$$\Pr_{x,y \in \mathbb{F}_2^n}[x^T M y = \sum M_{ij} x_i y_j \neq 0] \geq 1/4 \quad \forall M \neq 0.$$

$$\text{Proof: } M \neq 0 \Rightarrow \exists \text{ a row } M_i \neq 0 \Rightarrow (M y)_i = \langle M_i, y \rangle.$$

$$\forall M_i \neq 0, \Pr_y[\langle M_i, y \rangle \neq 0] = 1/2 \Rightarrow \text{w.p. } \geq 1/2, M y \neq 0.$$

$$\rightarrow \Pr_x[\langle x, M y \rangle \neq 0] \geq \Pr[M y \neq 0] \cdot \Pr[\langle x, M y \rangle \neq 0 \mid M y \neq 0] \geq \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4} //$$

$$\Rightarrow H(xy^T) - L(x) \cdot L(y) = x^T H y - x^T l l^T y = x^T (H - l l^T) y. \text{ If } H - l l^T \neq 0,$$

by the above fact, $\Pr[x^T (H - l l^T) y \neq 0] \geq 1/4. \Rightarrow \text{can detect } H \neq l l^T \text{ w.p. } \geq 1/4.$

Now, take a random linear combination of constraints $\{q_i\}$. This can just be written as some $\sum A_{ij} l_i l_j + \sum b_i l_i + C = H(A_{ij}) + L(b) + C = 0$.

If any of $q_1(l), \dots, q_k(l)$ are not 0, w.p. $\frac{1}{2}$, $\Pr[\sum_i r_i q_i(l) \neq 0] \geq \frac{1}{2}$.

* Soundness Boosting for Lin. Test: say we sample $x, y \in \mathbb{F}_2^n$ t times.

If f is ϵ -far from linear, $\text{Prob}[\text{success}] \leq (1 - \epsilon)^t$ with $3t$ bits of reading. For t bits, best possible soundness is $\frac{1}{2^t}$.

* PCP that reads t bits accept wrong proof w.p. $\frac{2t}{2^t}$.

Suppose S : $NP \subseteq PCP(t, \text{poly}(n), \epsilon) \Leftrightarrow \exists$ a CSP with constraints on t bits s.t. it is NP-hard to approximate better than ϵ -factor.

For $\epsilon = \frac{2t}{2^t}$, if $S(\epsilon)$ is true, $\forall$ CSPs with constraints on t bits, $\exists$ a $\frac{2t}{2^t}$ -factor approximation algorithm.

Expander Graphs

Most connected graph: K_n , $\binom{n}{2}$ edges. To break K_n , we need to delete a constant fraction of edges.

Def) Edge Expansion: For $G(V, E)$, $\forall S \subseteq V$ s.t. $|S| \leq \frac{n}{2}$, $\phi(S) = \frac{E(S, \bar{S})}{d|S|}$.
 ↳ Also, $\phi(S) = \Pr_{u \in N(v)} [u \notin S]$ where $N(v)$ is neighbors of v .
 ratio of edges crossing $S \rightarrow \bar{S}$
 # of edges incident in S

Def) Conductance: $\phi(G) = \min_{|S| \leq n/2} \sum \phi(S)$.

Def) Expander (1): a d -regular graph $G(V, E)$ is a (α, d) -expander if $\phi(G) \geq \alpha = \Omega(1)$. (combinatorial)

Theorem) [LPS] $\exists$ constant degree expander graphs with constant expansion.

$\hookrightarrow$ Pick a prime p . Vertices are $\{0, 1, \dots, (p-1), \infty\}$. Edges are:

$$x \rightarrow x+1 \pmod{p}, x \rightarrow x-1 \pmod{p}, x \rightarrow 1/x \pmod{p}.$$

This is a degree-3 graph and is an expander.

Theorem) A random d -regular graph is an expander w.h.p.

* Notation: Adjacency Matrix $A_{ij} := \mathbb{1}\{(i, j) \in E\}$.

Fact) Every real symmetric matrix A has:

1) n orthonormal eigenvectors $\vec{v}_1, \dots, \vec{v}_n$ with eigenvalue $\lambda_1, \dots, \lambda_n$.

$$\hookrightarrow A = \sum_i \lambda_i \vec{v}_i \vec{v}_i^T. \text{ for } \lambda_1 > \lambda_2 > \dots > \lambda_n, \lambda_1 = \max_{x \in \mathbb{R}^n} \left\{ \frac{x^T A x}{\|x\|^2} \right\}, \lambda_2 = \max_{x \perp \vec{v}_1} \{ \}$$

Def) Expander (2): A d -regular graph is a (d, λ) expander if

$$\max\{\lambda_2, |\lambda_n|\} \leq \lambda. \text{ (spectral)}$$

$\forall d$ -regular graph, $\lambda_1 = d$, $\vec{v}_1 = \vec{1}$, and all other λ s live in range $[-d, d]$.

Theorem) In a d -regular graph, $\phi(G)^2 \leq 1 - \lambda/d \leq 2\phi(G)$, where $\lambda := \max\{\lambda_2, |\lambda_n|\}$ $\hookrightarrow$ Cheeger's Inequality.

$$A = d \cdot \vec{1} \cdot \vec{1}^T + \sum_{i,j=1}^M \lambda_{ij} \vec{v}_i \vec{v}_j^T \quad \text{where } \vec{1} := [\frac{1}{\sqrt{n}}, \dots, \frac{1}{\sqrt{n}}].$$

For a complete graph, $A_c = \vec{1} \cdot \vec{1}$. So, if M is "negligible", A feels like a complete graph! $\rightarrow \|M\| = \max\{\lambda_2, |\lambda_n|\} = \lambda, \|Mx\| < \lambda\|x\|$.

$$\text{Claim) } \phi(G) \geq \frac{1}{2} \left(1 - \frac{\max\{\lambda_2, |\lambda_n|\}}{d} \right).$$

Proof: Fix a set S . Let $\vec{1}_S = [1_{\{v_1 \in S\}}, \dots, 1_{\{v_n \in S\}}]$.

$$\vec{1}_S^T A \vec{1}_S = \sum_{i,j} A_{ij} \cdot 1_S(i) \cdot 1_S(j) = \sum_{i,j \in S} A_{ij} = 2E(S, S).$$

$$\text{Then, } E(S, \bar{S}) = d|S| - E(S, S) = d|S| - \vec{1}_S^T A \vec{1}_S.$$

$$\rightarrow \phi(S) = 1 - \frac{\vec{1}_S^T A \vec{1}_S}{d|S|}. \quad \text{We define a new graph } L \text{ as such:}$$

Def) Laplacian Matrix: $L := d(I_d) - A$.

$$\vec{x}^T A \vec{x} = 2 \sum_{(i,j) \in E} x_i x_j. \quad \vec{x}^T L \vec{x} = \sum_{(i,j) \in E} (x_i - x_j)^2 = d \sum_i x_i^2 - 2 \sum_{(i,j) \in E} x_i x_j.$$

$$\lambda_1(L) = d - \lambda_1(A), \lambda_2(L) = d - \lambda_2(A), \dots$$

$$\phi(S) = \frac{E(S, \bar{S})}{|S|}.$$

$$\text{Claim: } E(S, \bar{S}) = \vec{1}_S^T L \vec{1}_S. \quad \sum_{(i,j) \in E} (1_S(i) - 1_S(j))^2 = \# \text{ of crossing edges.}$$

$\hookrightarrow 1_{\{i,j\}} \text{ crosses } S \rightarrow \bar{S}$

$$\begin{aligned} \rightarrow \vec{I}_s &= \underbrace{\frac{|\vec{S}|}{\sqrt{n}}}_{\alpha} \cdot \vec{I} + \vec{V} \text{ where } \vec{V} \perp \vec{I}. \left(\frac{|\vec{S}|}{\sqrt{n}} \text{ is } \langle \vec{I}, \vec{I}_s \rangle \right) \quad \begin{matrix} \nearrow \\ \geq (d-\lambda) \end{matrix} \\ \rightarrow \vec{u}^T \vec{I}_s &= \sum_i \lambda_i(L) \cdot \langle \vec{v}_i, \vec{u} \rangle^2 \rightarrow \vec{I}_s^T \vec{I}_s = \lambda_1(L) \cdot \langle \vec{I}_s, \vec{I} \rangle^2 + \sum_{i>1} \lambda_i(L) \langle \vec{I}_s, \vec{v}_i \rangle^2 \\ &\geq (d-\lambda) \cdot \sum_{i>1} \langle \vec{I}_s, \vec{v}_i \rangle^2. \quad \left(\|\vec{I}_s\| = \sqrt{S}, \|\vec{V}\|^2 = |\vec{S}| - \frac{|\vec{S}|^2}{n} = |\vec{S}| \left(1 - \frac{|\vec{S}|}{n}\right) \right) \\ &\geq (d-\lambda) \cdot |\vec{S}| \cdot \left(1 - \frac{|\vec{S}|}{n}\right) \rightarrow \phi(S) = \frac{E(S, \vec{S})}{d|\vec{S}|} = \left(1 - \frac{\lambda}{d}\right) \left(1 - \frac{|\vec{S}|}{n}\right) \geq \frac{1}{2} \left(1 - \frac{\lambda}{d}\right). \end{aligned}$$

Def) Expander (3): Graphs on which random walks "mix" in $\Theta(\log n)$ steps. π_u^t := distribution of endpoint v after t steps, i.e. in $t = \Theta(\log n)$ steps, $\|\pi_u^t - \text{Uniform}\| \leq \frac{1}{n^2}$.

Fact) $\pi_u^{t+1} = \frac{1}{d} \cdot A \cdot \pi_u^t$. In particular, $\pi_u^t = \left(\frac{A}{d}\right)^t \pi_u^0$.

Fact) Expander Graphs behave like Complete Graphs.

↳ Expander Mixing Lemma: G is a (n, d, λ) expansion. $S, T \subseteq V$. SNT = ∅?

$\frac{E(S, T)}{|E|}$ is how much of the edges cross $S \rightarrow T$. For a complete graph K_n , this is $\frac{|\vec{S}| \cdot |\vec{T}|}{\binom{n}{2}}$. $\left| \frac{E(S, T)}{|E|} - \frac{|\vec{S}| \cdot |\vec{T}|}{\binom{n}{2}} \right| \leq \lambda \sqrt{\frac{|\vec{S}| \cdot |\vec{T}|}{n^2}}$

Application) Reduce the randomness needed for error reduction.

Setup: A is a random algo. $\Pr_x[A(x, r) \text{ is correct}] \geq 0.6$.

Run $A(x, r_1), \dots, A(x, r_k)$ and return the majority vote.

Total randomness used is $k \cdot |r|$ bits. Success prob = $O(1 - e^{-\Omega(k)})$.

Idea: Let A use R bits of randomness. Fix an expander graph on vertices $\{0,1\}^R$. Let $r_1 :=$ new random point on $\{0,1\}^R$.

$r_2 \dots r_k$ are generated by a random walk in the expander.

Use $r_1 \dots r_k$ as the random bits for trials of A . We only need $R + k \log(d)$ randomness and $r_1 \dots r_k$ still satisfies randomness properties of A .

Lemma 1) Let $G(V,E)$ be a (n, d, λ) -expander. Let $F \subseteq E$ be a subset of the edges. $\lambda^{(A)} = \max\{\lambda_2, \lambda_n\}$ "bad edges"

$\Pr[t\text{-th step of walk} \in F \mid 0\text{-th step} \in F] \leq \frac{|F|}{|E|} + \left(\frac{\lambda}{d}\right)^{t-1}$.

Proof: Let $v :=$ starting point. Let $Y_v := |F \cap N(v)|/d$ (prop. of bad edges)

Let $X_v := \Pr[v \text{ is the first vertex} \mid 0\text{-th step} \in F] = \frac{|F \cap N(v)|}{|F|} \cdot \frac{1}{2} = \frac{d Y_v}{2|F|}$.

Then, $\bar{A}^{t-1} \cdot \vec{x} =$ prob. dist. of w (vertex after $t-1$ steps) where $\bar{A} = \left(\frac{A}{d}\right)$.

$P = \sum_w (\bar{A}^{t-1} \cdot \vec{x})_w \cdot Y_w$ ([prob. that $(t-1)$ -th vertex is w] $\cdot$ [t-th step $\in F \mid w$]).

$\vec{x} = \vec{x}'' + \vec{x}^\perp$ where $\vec{x}''$ is the component along $\vec{1}$ and $\vec{x}^\perp$ is orth. to $\vec{1}$.

$\vec{x}'' = \langle \vec{x}, \vec{1}(\frac{1}{n}) \rangle \cdot \left(\vec{1}(\frac{1}{n})\right) = \left(\sum \vec{x}''\right) \cdot \frac{1}{n} \cdot \vec{1} = \frac{1}{n} \vec{1}. (\bar{A} \vec{1} = \vec{1})$

$\bar{A}^{t-1} \vec{x} = \bar{A}^{t-1} \vec{x}'' + \bar{A}^{t-1} \vec{x}^\perp = \vec{x}'' + \left(\frac{A}{d}\right)^{t-1} \vec{x}^\perp$.

$P = \langle \bar{A}^{t-1} \vec{x}, \vec{y} \rangle = \frac{2|F|}{d} \langle \bar{A}^{t-1} \vec{x}, \vec{x} \rangle = \frac{2|F|}{d} \langle \vec{x}'' + \left(\frac{A}{d}\right)^{t-1} \vec{x}^\perp, \vec{x}'' + \vec{x}^\perp \rangle$

$$= \frac{2|F|}{d} \left[\langle \vec{x}^0, \vec{x}^0 \rangle + \langle \left(\frac{A}{d}\right)^{t-1} \vec{x}^\perp, \vec{x}^\perp \rangle \right] \quad (\text{since } \vec{x}^0 \perp \vec{x}^\perp, \left(\frac{A}{d}\right)^{t-1} \vec{x}^0 = \vec{x}^0)$$

$$\leq \frac{2|F|}{d} \left(\frac{1}{n} + \left\| \left(\frac{A}{d}\right)^{t-1} \vec{x}^\perp \right\| \cdot \left\| \vec{x}^\perp \right\| \right) \quad (\text{Cauchy-Schwartz})$$

$$\leq \frac{2|F|}{d} \left(\frac{1}{n} + \left\{ \left(\frac{\lambda}{d}\right)^{t-1} \cdot \left\| \vec{x}^\perp \right\|^2 \right\} \cdot \left\| \vec{x}^\perp \right\| \right), \text{ and use the bound } \left\| \vec{x}^\perp \right\|^2 \leq \left\| \vec{x} \right\|^2.$$

$$* \left\| \vec{x} \right\|^2 = \sum_v x_v^2 \leq \sum_v \overset{1}{x_v} \cdot (\max_w x_w) = \max_w (x_w) = \max_w \left(\frac{|F \cap N(w)|}{2|F|} \right) \leq \frac{d}{2|F|}.$$

$$\rightarrow \leq \frac{2|F|}{d} \left(\frac{1}{n} + \left(\frac{\lambda}{d}\right)^{t-1} \cdot \frac{d}{2|F|} \right) = \frac{|F|}{|E|} + \left(\frac{\lambda}{d}\right)^{t-1}.$$

Upshot: no matter how F is selected, we can "escape" F w.h.p.

Dinur's PCP Proof

Recall: PCP Theorem $\Rightarrow NP \subseteq PCP(\overset{\text{queries}}{q}, \overset{\text{length of proof}}{L})$ $(\Sigma = k)$

Def) 2CSP: Given by $G(V, E)$, a constraint graph, a constant size Σ .
 $\nearrow$ variables
 $\nwarrow$ constraints

An assignment is $\sigma: V \rightarrow \Sigma$. Constraints are $\{C_e \subseteq \Sigma \times \Sigma \mid e \in E\}$.
 $\nearrow$ set of allowed config of edge e .

σ satisfies edge $e = (u, v)$ if $(\sigma(u), \sigma(v)) \in C_e$. The value of σ ,

$\text{Val}(\sigma) = \text{fraction of constraints satisfied} = \frac{1}{|E|} \cdot (\# \text{ of edges satisfied by } \sigma).$

$\text{OPT}(G) = \max_{\sigma} \{ \text{Val}(\sigma) \}$. $\text{gap}(G) = 1 - \text{OPT}(G).$

MAX-2CSP: Given $G(V, E)$, compute $\text{OPT}(G)$.

Proof of PCP Theorem: $3\text{SAT}(\phi) \xrightarrow{\text{some NP-C problem}} 2\text{CSP}(G)$ preserving completeness (ϕ is satisfiable $\Rightarrow \text{OPT}(G) = 1$) and soundness (ϕ is

unsatisfiable $\Rightarrow \text{OPT}(G) < 0.9, \text{gap} > 0.1$.

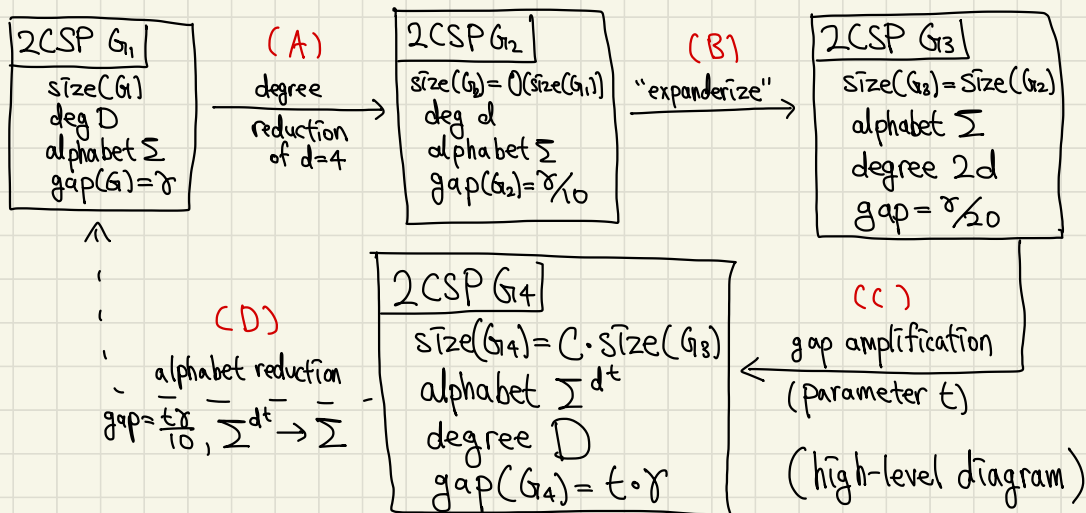
Idea: Pick 3-Coloring for Φ , which is already a 2-CSP.

$3\text{COL} \in \text{NP-C.} \Rightarrow \text{Completeness: } \text{gap}(G) = 0$. Soundness: $\forall$ coloring of graph G , $\exists$ a violated edge $\Rightarrow \text{gap}(G) \geq \frac{1}{|E|} \approx \frac{1}{n^2}$. ^{how to make this a constant?}

Idea: Perform a series of reductions to amplify the gap to, say, 0.1.

The Reduction: $\boxed{\begin{array}{l} \text{2CSP} \\ \text{size}(G) = n \\ \text{gap}(G) = \gamma \cdot \Sigma \end{array} \left[\begin{array}{l} G \\ \end{array} \right]} \rightarrow \boxed{\begin{array}{l} \text{2CSP} \\ \text{size}(G') = \alpha n \\ \text{gap}(G') = 2\gamma \cdot \Sigma \end{array} \left[\begin{array}{l} G' \\ \end{array} \right]}$

$\hookrightarrow$ repeat this reduction $\Theta(\log n)$ times, starting from $3\text{-COL}(G)$. Then, $\text{size}(G^*) = c^{\log n} \cdot n = \text{poly}(n)$, while gap is amplified.



(A) Degree Reduction: $\text{deg}(G) = D$. Produce a reduction to G' s.t. $\text{deg}(G') = 4$.

Suppose $\exists v$ with >4 constraints. Make D copies of it, $v_1, v_2, \dots, v_D$. Assign

a single edge to each of them. Then, connect $v_1, \dots, v_0$ with a degree 3 expander of equality constraints. $\rightarrow$ # of vertices in $G' =$ # of edges in G , and $\deg(G') = 3 + 1$ (3 for expander, 1 for single edge).

Soundness: Suppose $\text{gap}(G) \geq \gamma \Rightarrow \text{gap}(G') \geq \gamma/40$. Call the set $\{v_1, \dots, v_0\}$ $\text{cloud}(v)$. Fix any assignment $\sigma': V(G') \rightarrow \Sigma$ for G' .

Define $\sigma: V(G) \rightarrow \Sigma$ where $\sigma(v) = \underset{\rightarrow \text{(most popular)}}{\text{Plurality}} \{ \sigma(v^{(i)}) \mid v^{(i)} \in \text{cloud}(v) \}$.

Define $\text{Bad}_v := \{ v^{(i)} \mid \sigma'(v^{(i)}) \neq \sigma(v) \}$, the vertices inconsistent with equality.

Proof of Soundness: $\forall$ original edge $(u^{(i)} \rightarrow v^{(i)}) \in \text{constraints in } G' \text{ from } G$,

if σ violates $(u^{(i)} \rightarrow v^{(i)})$, then either 1) σ' also violates that constraint,

or 2) $\sigma(u) \neq \sigma'(u^{(i)})$ or 3) $\sigma(v) \neq \sigma(v^{(i)})$. Then, # of edges

violated by $\sigma \leq$ # of original edges violated by $\sigma' + \sum_v |\text{Bad}_v|$ (union).

Also, # of edges violated by $\sigma \geq \gamma \cdot |E|$.

$\Rightarrow \underbrace{\# \text{ of original edges violated by } \sigma'}_{\alpha} + \sum_v |\text{Bad}_v| \geq \gamma \cdot |E|$.

Case 1) $\alpha \geq \gamma/2 \cdot |E| \geq \gamma/8 \cdot |E'|$ since $|E'| = 5/2 |E|$ (some constant mult)

Case 2) $\sum_v |\text{Bad}_v| \geq \gamma/2 |E|$, total # of minority vertices $\geq \gamma/2 \cdot |E|$. By expansion of degree-3 graphs, in $\text{cloud}(v)$, at least $|\text{Bad}_v|/5$ equality constraints are violated (some constant fraction). $\Rightarrow$ # of violated constraints $\geq \sum_v |\text{Bad}_v|/5 \geq \gamma/10 |E| \geq \gamma/40 |E'|$. //

(B) Expanderizing: $\deg(G) = 4$, but not an expander. $\text{gap}(G) = \gamma/40$.

$G' = G \cup H$ where $H :=$ some degree-4 expander. $V(G') = V(G)$, but $E(G') = E(G) \cup E(H)$. Constraints on H are trivial $c_e = \sum_{v \in H} x_v$ $\rightarrow$ all possible pairs
 $\text{gap}(G') = \text{gap}(G)/2$.

(C) Gap Amplification: G is a (n, d, λ) -spectral expander $\rightarrow G'$.

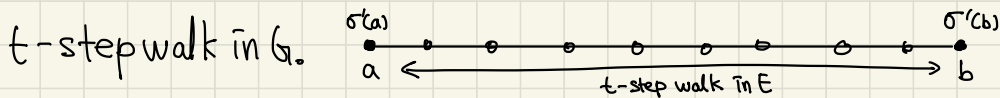
Idea: $V' = V$. For assignment in G , $\sigma: V \rightarrow \Sigma$, in G' , $\sigma'(v) :=$

"opinion of v on all vertices up to distance t ", i.e. $\forall w$ s.t. $\text{dist}(v, w) \leq t$,

$(\sigma'(v))_w \in \Sigma$, which is " v 's opinion on value on value to be assigned to w ".

$|\sigma'(v)| < 1 + d + d^2 + \dots + d^t$. Thus, $\sigma': V \rightarrow \Sigma^{1+d+\dots+d^t}$. Constraints are:

$E' := \{ \text{all "t-step" } \overset{\text{random}}{\text{walks}} \text{ in } G \}$, i.e. $(a, b) \in E' \Leftrightarrow (a, b)$ are endpoints of a t -step walk in G .



$\sigma'(a)$ holds opinion on all vertices on the path, as well as $\sigma'(b)$.

Check if they are consistent along all vertices on the path AND that they satisfy the constraints on each edges on the path.

Completeness: If $\exists \sigma$ satisfying G , then let σ' be constructed by it. „

Soundness Goal: If $\text{gap}(G) = \gamma$, then we want $\text{gap}(G') \geq t\gamma$.

$\hookrightarrow \sigma'$ is any assignment, and it will violate $t\gamma |E'|$ or more edges.

Proof Strategy: Use σ' to define an assignment $\sigma: V \rightarrow \Sigma$. Define $\sigma(u) := \text{Plurality} \{ (\sigma'(v))_u \mid v \in N_t(u) \}$ ($*N_t(u)$ means t -distance neighbors of u)

Since $\text{gap}(G) \geq \gamma$, σ violates γ -fraction of edges. Let $F := \{ \text{edges violated by } \sigma \} \subseteq E$. Consider a t -step walk in G (an edge in G'). If the walk contains an edge in F , say (u, v) , $(\sigma(u), \sigma(v))$ violates it.

Since σ is a majority vote, $(\sigma'(a))_u \simeq \sigma(u)$, and $(\sigma'(b))_v \simeq \sigma(v)$, and the "average" opinion of a and b also violates (u, v) , thus $(\sigma'(a), \sigma'(b))$ violates the t -step walk. $\Rightarrow$ When a t -step walk contains an edge in F , the t -step walk is violated. (w.c.p., intuitively)

In an expander graph, every step of a walk is a "random edge".
 $\hookrightarrow \Pr[\text{hit an edge in } F \text{ in a } t\text{-step walk}] \simeq 1 - (1 - \gamma)^t \simeq t \gamma^{\overrightarrow{\text{gap of } G'}}$

Formalisms: First, we concretely define "t-step walks".

Def) After Stopping Random Walk (ASRW):

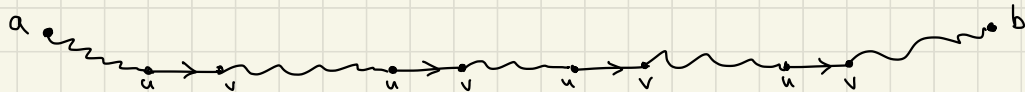
1) Pick $v \in V$ u.a.r. 2) Take a random step to a neighbor.

3) Stop w.p. $1/t$. 4) Else, go to step 2. $\rightarrow E[\text{length of walk}] = 1 + t$.

Def) Before Stopping Random Walk (BSRW): Interchange steps 2 and 3 from ASRW. $E[\text{length of walk}] = t$.

↳ In both cases, $E[\text{length of walk}] \simeq t$, mimicking a t -step walk. $\Theta_{u \rightarrow v, \leq k}$

Lemma) Fix a $k \in \mathbb{N}$, $G(V, E)$. Consider $[\text{ASRW} \mid \text{exactly } k \text{ steps on edge } (u, v)]$.



- 1) Distribution of b in $\Theta_{u \rightarrow v, \leq k} \equiv \text{BSRW}$ starting at v w.p. $1/t$.
- 2) Distribution of a in $\Theta_{u \rightarrow v, \leq k} \equiv \text{ASRW}$ starting at u w.p. $1/t$.
- 3) a and b are independent.

Consider $\Theta_{u \rightarrow v, \geq k} := [\text{ASRW} \mid \text{at least } k \text{ steps on } (u, v)]$. It satisfies the above 1, 2, 3. $\Theta_{u \rightarrow v, \geq k} = \Theta_{u \rightarrow v, \geq k} - \Theta_{u \rightarrow v, \geq (k-1)}$ with abuse of notation, and the "subtraction" of two distributions still preserves properties.,,,

(of $O(t \ln \Sigma)$ steps)

Now, we formally define $E' := \{ \text{all ASRWs in } G_t \}$, i.e. $(a, b) \in E' \iff (a, b) \text{ are endpoints of an ASRW. Then, } G'$ is a weighted multigraph.

We can normalize all weights into integers, then replace them with multiedges.

For $\forall$ edge $u \rightarrow v$ in walk s.t. $\text{dist}(a, u) \leq t$ AND $\text{dist}(b, v) \leq t$, check whether $(\sigma'(a)_u, \sigma'(b)_v)$ satisfy the constraint on (u, v) .

Formal Proof: Start with $\sigma': V \rightarrow \sum^{t+\dots+t}$ in G' . Define $\sigma(v) :=$

Plurality $\{ (\sigma'(b))_v \mid b \text{ is an endpoint of BSRW starting at } v \wedge \text{dist}(b, v) \leq t \}$

σ must violate the set of edges F where $|F| \geq \gamma |E|$ ($\because \text{gap}(G) \geq \gamma$).

Def) Faulty Step: In an ASRW $a \rightsquigarrow b$, an edge $u \rightarrow v$ is a faulty step if:

1) $(\sigma'(a))_u = \sigma(u)$ 2) $(\sigma'(b))_v = \sigma(v)$ 3) $(\sigma(u), \sigma(v))$ violate constraint (u, v) .

Obs) If an ASRW $a \rightsquigarrow b$ has a faulty step, constraint (a, b) is violated by σ' .

$\Pr[\text{ASRW } a \rightsquigarrow b \text{ is violated by } \sigma'] \geq \Pr[\exists \text{ faulty step } u \rightarrow v \in a \rightsquigarrow b]$.

Define $S := \#$ of steps of a walk, $N_F := \#$ of steps that are faulty edges

$N := \#$ of faulty steps in ASRW. $N_* := N \cdot \mathbb{1}\{S \leq B\}$. ($B = \Theta(t \ln \Sigma)$)

$\Rightarrow \Pr[\exists \text{ a faulty step } u \rightarrow v \in a \rightsquigarrow b] = \Pr[N_* > 0]$. (observe $N_* \leq N \leq N_F$)

Goal: $\Pr[N_* > 0] \geq \frac{E[N_*]^2}{E[N_*^2]} \xrightarrow{\text{lower bound}} \xrightarrow{\text{upper bound}} \geq t\gamma$. (second moment)

$$\begin{aligned} E[S] &= t+1. \quad E[N_F | S=l] = \sum_{i=1}^l E[\mathbb{1}\{i\text{-th step} \in F\}] = \sum_{t=1}^l \sum_{(u,v) \in F} E[\mathbb{1}\{t\text{-th step} = (u,v)\}] \\ &= \sum_{t=1}^l \sum_{(u,v) \in F} \Pr[t\text{-th step} = (u,v)] = \sum_{t=1}^l \sum_{(u,v) \in F} \frac{1}{|\Sigma|} = \frac{l}{|\Sigma|} \cdot |\Sigma|. \quad E[N] = \sum_{t=1}^{\infty} \sum_{(u,v) \in F} E[\mathbb{1}\{t\text{-th step is a} \\ &\text{faulty step on } (u,v)\}] = \sum_{(u,v) \in F} \sum_{t=1}^{\infty} \Pr[t\text{-th step is } (u,v) \text{ and } (u,v) \text{ is faulty}] = \sum_{(u,v) \in F} E[(\# \text{ of } (u,v) \\ &\text{steps}) \times \mathbb{1}\{(u,v) \text{ is a faulty step}\}] = \sum_{(u,v) \in F} \sum_{k=1}^{\infty} k \cdot \Pr[\# \text{ of } (u,v) \text{ steps} = k] \cdot \Pr[(u,v) \text{ is a faulty} \\ &\text{step} \mid \# \text{ of } (u,v) \text{ steps} = k]. \end{aligned}$$

$$\Pr[(\sigma'(a))_u = \sigma(u), (\sigma'(b))_v = \sigma(v) \mid \#(u,v) \text{ steps} = k]$$

$$= \Pr[(\sigma'(a))_u = \sigma(u) \mid \#(u,v) \text{ steps} = k] \cdot \Pr[(\sigma'(b))_v = \sigma(v) \mid \#(u,v) \text{ steps} = k]$$

$$= \Pr_{\text{BSRW from } u}[(\sigma'(a))_u = \sigma(u)] \Pr_{\text{BSRW from } v}[(\sigma'(b))_v = \sigma(v)] \geq \left(\frac{1}{|\Sigma|}\right) \left(\frac{1}{|\Sigma|}\right) = \Theta\left(t\gamma \frac{1}{|\Sigma|}\right)$$

$$\rightarrow \geq \frac{1}{|\Sigma|^2} \sum_{(u,v) \in F} \sum_{k=1}^{\infty} k \cdot \Pr[\# \text{ of } (u,v) \text{ steps} = k] = \frac{1}{|\Sigma|^2} \cdot E[N_F] \geq (t+1) \cdot \frac{|\Sigma|}{|\Sigma|^2} \cdot \frac{1}{|\Sigma|^2} //$$

$$E[N_*] = E[N \cdot \mathbb{1}\{S \leq B\}] \geq \frac{t\gamma}{8|\Sigma|^2} \text{ (without proof).}$$

$$E[N^{*2}] \leq E[N^2] \leq E[N_F^2] = E\left[\left(\sum_i \chi_i\right)^2\right] \text{ where } \chi_i := \mathbb{1}\{\text{i-th step} \in F\}.$$

$$\rightarrow \sum_{i=1}^{\infty} E[\chi_i] + 2 \sum_{i=1}^{\infty} \sum_{j>i} E[\chi_i \chi_j] = E[N_F] + 2 \sum_{i=1}^{\infty} \Pr[i\text{-th} \in F] \sum_{j>i} \Pr[j\text{-th} \in F | i\text{-th} \in F].$$

Reminder: G is a (n, d, λ) -expander, $F \subseteq E$. Then,

$$\begin{aligned} \Pr[(t+1)\text{-th step} \in F | t\text{-th step} \in F] &\leq \frac{|F|}{|E|} + \left(\frac{\lambda}{d}\right)^t. \quad \xrightarrow{(1-1/t)^{t-i}} \leq \frac{|F|}{|E|} + \left(\frac{\lambda}{d}\right)^{t-i} \\ &\rightarrow \leq E[N_F] + 2 \sum_{i=1}^{\infty} \underbrace{\Pr[i\text{-th} \in F]}_{\frac{|F|}{|E|}} \cdot \underbrace{\Pr[\# \text{ of extra steps} \geq j-i]}_{(1-1/t)^{j-i}} \cdot \underbrace{\Pr[j\text{-th} \in F | i\text{-th} \in F]}_{\leq \frac{|F|}{|E|} + \left(\frac{\lambda}{d}\right)^{j-i}} \\ &\leq t \cdot \frac{|F|}{|E|} = \Omega(tr). \Rightarrow \Pr[N_* > 0] \geq \frac{\Omega(t^2 r^2)}{\Theta(tr)} \geq tr. // \end{aligned}$$

(D)

Alphabet Reduction: $G(V, E), \Sigma = [2^k]$. constraint $C_{uv} \subseteq \Sigma \times \Sigma$.

$u, v \in \{l\text{-bit strings}\}$. we want a constant # of bits. Consider the PCP

verifier that reads $(u, v) \in E$ and verifies $(\sigma(u), \sigma(v))$ satisfies constraints _{C_{uv}} .

↳ This reads $2l$ bits now, but can we reduce # of bits read?

⇔ How to check if $(\sigma(u), \sigma(v))$ satisfies C_{uv} by reading $\leq 2l$ bits?

↳ Solve by recursion, or, an exponential-sized PCP (proof composition)

Recall: For a circuit C with k bit input, $\exists$ a PCP of size $2^{\Omega(k)}$ s.t. by reading $2l$ bits of the proof, we can check that $\exists z$ s.t. $C(z) = 1$.

↳ Our circuit is $C(\sigma(u), \sigma(v)) = \mathbb{1}\{\sigma(u), \sigma(v) \text{ satisfies } C_{uv}\}$.

⇒ prover gives exp-sized proof that "Circuit C_{uv} is satisfiable". But is

$(\sigma(u), \sigma(v))$ satisfiable, i.e. $C_{uv}(\sigma(u), \sigma(v)) = 1$??

Digression: Assignment Testers (PCP Proximity Test)

Def) Reduction Algorithm: A q -query tester $AT(\gamma > 0, \Sigma)$ is a RA P ,

$P: \{\text{Boolean Circuit } C\} \rightarrow \{\text{Constraint System } \Gamma \text{ of 1) Boolean variables } X,$

2) Auxillary Variables $Y\}$. Γ satisfies properties:

1) If $C(X) = 1$, then $\exists Y$ s.t. (X, Y) satisfy all constraints of Γ .

2) If X is δ -far from any satisfying assignments, then $\text{gap}(\Gamma) \geq \gamma \cdot \delta$.

$\Leftrightarrow \forall Y, (X, Y)$ violates $\gamma \cdot \delta$ constraints.

$\hookrightarrow$ Checks if X is close to a real satisfying solution to C .

$\Rightarrow$ Now, verifier can check if C_w is satisfied by something close to $(\sigma(w), \sigma(v))$.

Let E , an error correcting code, $:\{0,1\}^l \rightarrow \{0,1\}^{100l}$ s.t. $\text{dist}^{Hamming}(E(\alpha), E(\beta)) \geq 0.3$. Then, use $E(\sigma(w))$ and $E(\sigma(v))$ (of each length $100l$) and some

modified constraint C'_w that checks 1) $\sigma'(w)$ & $\sigma'(v)$ are valid codewords and 2) $E^{-1}(\sigma'(w))$ & $E^{-1}(\sigma'(v))$ satisfies C_w . A proximity tester for

C' will then give whether $(\sigma'(w), \sigma'(v))$ is close to satisfying C' . But in the codomain of E , being close is equivalent to being equal since every point is sparse. Thus, proximity testing suffices for testing C_w .

Fix $\sigma': V' \rightarrow \{0,1\}^{100l}$. If $\text{gap}(G) \geq \epsilon \Rightarrow AT$ rejects w.p. $\epsilon/100$.

Define $\sigma(u) :=$ nearest codeword decoding of $\sigma'(u) \in \{0,1\}^L$. We know that $\sigma(u)$ violates $\text{gap}(G)$ constraints. Suppose edge (u,v) is violated by σ . Then, nearest code words to $\sigma'(u)$ & $\sigma'(v)$ violate C_{uv} .

$\Rightarrow (\sigma'(u), \sigma'(v))$ is far from satisfying C_{uv} (by virtue of being close to a wrong one).

$\nearrow$ q -query PCP $\nearrow$ 2-query PCP

Reduction from $Q\text{-CSP} \rightarrow 2\text{-CSP}$: Let $Q\text{-CSP} = 3\text{-SAT}$. $C_1, \dots, C_m$ are clauses, $X_1, \dots, X_n$ are variables. For (clause - variable) edge, constraint is consistency between $C_i = (a \vee b \vee c)$ and $V_j = 0$ or 1 . If $\text{gap}(3\text{SAT-instance}) = \gamma$, $\text{gap}(\text{graph}) \geq \frac{\gamma}{3}$. $\Rightarrow$ AT can be reduced to 2-queries.

Recall: For Exp-sized PCP for Circuit-SAT, to check $\exists x$ s.t. $C(x) = 1$, we constructed a reduction to a system of quadratic equations. The prover wrote down a Hadamard encoding of Z and ZZ^T , where they claim that Z satisfies all of the quad eqs. $\rightarrow$ constructs AT as desired.

SDP-Based Algorithms

MAXCUT: $G(V,E) \rightarrow (S, \bar{S})$ s.t. $|E(S, \bar{S})|/|E|$ is maximized.

$\hookrightarrow$ can be thought of as a CSP that assigns $\{0,1\}$ membership to S .

$\Rightarrow$ NP-Hard to solve exactly, how well can we approximate it?

PCP says that as long as $P \neq NP$, $\exists \varepsilon \ll 1$ s.t. $\nexists$ a $(1-\varepsilon)$ -approx. factor.

$\hookrightarrow \therefore$ we proved a reduction of $(\overset{(G)}{NP-C}) \rightarrow (\overset{(H)}{\text{Gap 2-CSP}})$ s.t.:

if 3-COL is satisfiable, $\text{gap}(H) = 0$, and if not, $\text{gap}(H) > \varepsilon$, say 10^{-6} .

If we have a more fine-grained approx. factor α , say 10^{-12} , then we have a decision oracle for an NP-C problem, so we cannot have it.

We can also reduce $(\overset{(H)}{\text{Gap 2-CSP}}) \rightarrow (\overset{(H')}{\text{MAXCUT}})$, where $\text{val}(H) = 1 \Rightarrow \text{val}(H') = \beta$, $\text{val}(H) < 1 - 10^{-6} \Rightarrow \text{val}(H') < (1 - 10^{-6}) \cdot \beta(1 - \delta)$.

Def) Positive Semi-Definiteness: symmetric $M \succeq 0$ iff,

1) $\lambda_i(M) \geq 0 \quad \forall i \in [n]$, 2) $M = VV^T$ where $v_1, \dots, v_n \in \mathbb{R}^n$ s.t. $\langle v_i, v_j \rangle = M_{ij}$.

3) $\forall v, v^T M v \geq 0$.

Fact: PSD in $\mathbb{R}^{n \times n}$ forms a convex cone, and $\exists$ a separation oracle s.t. if $M' \notin \text{PSD}(\mathbb{R}^{n \times n})$, we can find a separating hyperplane between PSD & M' .

$\hookrightarrow M'$ has a negative $\lambda_i(M')$ w/ v , so $v^T M' v < 0 \Rightarrow \sum M'_{ij} v_i v_j < 0$.

Then, since $\forall M \in \text{PSD}, v^T M v \geq 0, \sum M_{ij} v_i v_j \geq 0$, so $f(M) = \sum M_{ij} v_i v_j$ is a separating oracle.

Naïve Rand. Algo.: $E[\# \text{ cuts}] = \frac{1}{2} |E|$. (not useful, a crude lower bound)

Consider a degree $D=100$ random graph and a bipartite graph of degree $D'=(1-\epsilon)D$. LP cannot distinguish between these, so it is no better than $1/2 |E|$.

[Goeman-Williamson]

SDP-based MAXCUT: $x_1, \dots, x_n$ are variables, $x_i = \begin{cases} +1 & \text{if } i \in S \\ -1 & \text{if } i \notin S \end{cases}$.

Obj: $\max_{x \in \{\pm 1\}^n} \text{Val}_G(x) = \frac{1}{|E|} \sum_{(i,j) \in E} \frac{(x_i - x_j)^2}{4}$ s.t. $(x_i - x_j)^2 = 4$ iff i, j are separated.

Relaxation: $x_i \in \{\pm 1\} \Rightarrow v_i \in \mathbb{R}^d$. Let $\text{OPT}_d = \max_{v_i \in \mathbb{R}^d, \|v_i\|=1} \sum_{(i,j) \in E} \|v_i - v_j\|^2$.

At $d=n$, OPT_n is actually a convex program (solvable in P)!

$$\begin{aligned} \hookrightarrow \text{OPT}_n &= \max_{v_i \in \mathbb{R}^n, \|v_i\|=1} \frac{1}{|E|} \sum_{(i,j) \in E} \frac{\|v_i - v_j\|^2}{4} = \max_{v_i \in \mathbb{R}^n, v_i \cdot v_i = 1} \frac{1}{|E|} \sum_{(i,j) \in E} \frac{(v_i - v_j) \cdot (v_i - v_j)}{4} \\ &\underset{\sim}{=} \max \frac{1}{|E|} \sum_{(i,j) \in E} \frac{(v_i \cdot v_i + v_j \cdot v_j - 2v_i \cdot v_j)}{4} \Rightarrow \max \frac{1}{|E|} \sum_{(i,j) \in E} v_i \cdot v_i + v_j \cdot v_j - 2v_i \cdot v_j \quad \text{sub. to } v_i \cdot v_i = 1. \end{aligned}$$

Now consider an LP defined $v_i \cdot v_i = M_{ii}$, $v_j \cdot v_j = M_{jj}$, $v_i \cdot v_j = M_{ij}$. Then,

$M = (M_{ij})$ is a PSD, and we can rewrite to $\max_M \frac{1}{|E|} \sum (M_{ii} + M_{jj} - 2M_{ij})$

subject to $M_{ii} = 1$ and $M \succeq 0$. Optimize over M to get $V = (v_1, \dots, v_n)$.

* SDP $\simeq$ LP over inner products of vectors $v_1, \dots, v_n \in \mathbb{R}^n \simeq$ Opt. over PSD cone.

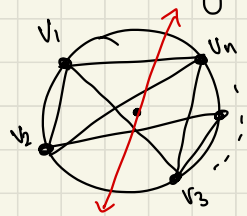
So $\text{OPT}_n(G) = \text{SDP}(G) \geq \text{MAXCUT}(G) = \text{OPT}_1(G)$. In a $\mathbb{R}^n$ unit

ball, the graph will now be embedded on the surface. Take a random

hyperplane cut through the origin, $H_r = \{x \in \mathbb{R}^n \mid r \cdot x = 0\}$.

Output $S = \{i \mid v_i \cdot r \geq 0\}$, $\bar{S} = \{i \mid v_i \cdot r < 0\}$. 0.818 factor.

(proof omitted)



Consider again $\max_{x \in \{\pm 1\}^n} \text{Val}_G(x)$. How do we "convexify" it? The most convenient way is to optimize over probability distributions.

$$\hookrightarrow \max_{\mu} \mathbb{E}_{x \sim \mu} [\text{Val}_G(x)] = \sum_{x \in \{\pm 1\}^n} \mu(x) \cdot \text{Val}_G(x) \text{ where } \mu(x) = \Pr[x \text{ is selected}]$$

Now, the set of all μ is convex. However, $|\mu| = 2^n$. Can we do better?

Def) Moments of μ : μ is a prob. dist. over $\in \{0, 1\}^n$. degree 1 moments are $\mathbb{E}_{x \sim \mu} [x_i], \dots, \mathbb{E}_{x \sim \mu} [x_n]$, degree 2 is $\mathbb{E}_{x \sim \mu} [x_i x_j], \dots$ and so on.

$$\mathbb{E}_{x \sim \mu} [\text{Val}_G(x)] = \mathbb{E}_{x \sim \mu} \left[\frac{1}{|E|} \sum_{(i,j) \in E} \frac{(x_i - x_j)^2}{4} \right] = \frac{1}{|E|} \sum_{(i,j) \in E} (\mathbb{E}_{x \sim \mu} [x_i^2] + \mathbb{E}_{x \sim \mu} [x_j^2] - 2\mathbb{E}_{x \sim \mu} [x_i x_j]) / 4$$

$\rightarrow$ this is a linear function over all deg. 2 moments of μ !

$$\Rightarrow (\text{lossy step}) \max_{\{\text{deg 2 moments}\}} \frac{1}{|E|} \sum_{(i,j) \in E} \frac{\mathbb{E}[x_i^2] + \mathbb{E}[x_j^2] - 2\mathbb{E}[x_i x_j]}{4}, \text{ let } X_{ij} := \mathbb{E}[x_i x_j].$$

$$\rightarrow \frac{1}{|E|} \max_{\{X_{ij}\}} \sum_{(i,j) \in E} X_{ii} + X_{jj} - 2X_{ij} \text{ sub. to } X_{ii} = 1, \text{ and } X \succeq 0. \text{ This is}$$

because moment matrices are PSD, and X is a deg. 2 moment matrix.

Then, this is a SDP problem. In fact, we can impose a deg. d moment matrix for a finer resolution of the constraint.

Current knowledge: for MAXCUT, deg 2 (SOS-SDP) $\rightarrow 0.878$ factor is the best known, and deg 4 $\rightarrow$ unknown?? However, under Unique Games Conjecture (an unproven hardness assumption), deg 2 SOS is indeed optimal in P.

i.e. it is NP-Hard to beat it (when the instance is not satisfiable).

The Whole Point: this scheme yields a more general way to SDP-fy any reasonable NP-Complete problem, say 3-SAT. And again, UGC says that deg. 2 SOS will be optimal (basic SDP relaxation).

Hastad's 3 Query PCP

$PCP(3 \text{ bits}, \text{poly}(n)) \rightarrow \underbrace{\text{Completeness } (1-\epsilon), \text{ Soundness } (\frac{1}{2} + \epsilon)}_{\text{The goal}}$

Fourier Analysis of the Boolean Cube: $\{0,1\}^n \equiv \mathbb{Z}_2^n$.

$x, y \in \{0,1\}^n \Rightarrow x \oplus y$, which is just $x+y \pmod{2}$ forms a group.

Def) Character: $\chi: \{0,1\}^n \rightarrow \mathbb{R}$ s.t. $\chi(a \oplus b) = \chi(a) \cdot \chi(b)$.

ex) $\chi_i: \{0,1\}^n \rightarrow \mathbb{R}$. $\chi_i(x) = (-1)^{x_i}$. $\chi(x \oplus y) = (-1)^{x_i \oplus y_i} = (-1)^{x_i} \cdot (-1)^{y_i}$

$\chi_i(x) = (-1)^{x_i}$ are characters.

The list of all characters: $\forall S \subseteq [n]$, $\chi_S(x) := (-1)^{\sum_{i \in S} x_i} = \prod_{i \in S} \chi_i(x_i)$.

Inner Product on functions on $\{0,1\}^n$: $\forall f, g: \{0,1\}^n \rightarrow \mathbb{R}$, $\langle f, g \rangle := \frac{1}{2^n} \sum_x f(x)g(x) =$

$\mathbb{E}_x[f(x)g(x)]$. This behaves well; $\langle \chi_i, 1 \rangle = \mathbb{E}_x[(-1)^{x_i} \cdot 1] = 0 \Rightarrow \langle \chi_S, 1 \rangle = 0 \quad \forall S \neq \emptyset$.

$\chi_S(x) \cdot \chi_T(x) = (-1)^{\sum_{i \in S} x_i} (-1)^{\sum_{i \in T} x_i} = (-1)^{\sum_{i \in S \Delta T} x_i} = \chi_{S \Delta T}(x) \Rightarrow \langle \chi_S, \chi_T \rangle = 0$ unless $S=T$.

$\langle \chi_S, \chi_S \rangle = \mathbb{E}_x[\chi_S(x)^2] = 1$. $\therefore \{\chi_S\}$ is an orthonormal basis of set of all $f: \{0,1\}^n$

$\Rightarrow$ we can write ANY function in the basis of χ_S !

$\rightarrow \mathbb{R}$.

Suppose $f: \{0,1\}^n \rightarrow \mathbb{R}$. Then, $f = \sum_s \langle f, \chi_s \rangle \cdot \chi_s = \sum_s \hat{f}_s \chi_s$ where $\hat{f}_s := \mathbb{E}_x [f(x) \cdot \chi_s(x)]$. Thus, $\{f(x) | x \in \{0,1\}^n\} \Leftrightarrow \{\hat{f}_s | s \subseteq [n]\}$.

Theorem) Parseval's Identity: Given $f: \{0,1\}^n \rightarrow \mathbb{R}$, $\|f\|^2 = \frac{1}{2^n} \sum_x f(x)^2 = \sum \hat{f}_s^2$.

Proof: $\|f\|^2 = \langle f, f \rangle = \langle \sum_s \hat{f}_s \chi_s, \sum_\tau \hat{f}_\tau \chi_\tau \rangle = \sum_s \hat{f}_s^2 + \sum_{s \neq \tau} \hat{f}_s \hat{f}_\tau \underbrace{\langle \chi_s, \chi_\tau \rangle}_0 = \sum_s \hat{f}_s^2$. //

Linearity Test: Given $f: \{0,1\}^n \rightarrow \{0,1\}$, test if f is close to linear, i.e.

$f(x) \simeq \sum_i b_i x_i$ for most x .

The Test: Pick $x, y \in \{0,1\}^n$. Test if $f(x) + f(y) = f(x+y)$.

Analysis: $\Pr_{x,y} [f(x) + f(y) - f(x+y) = 0]$? Define $F(x) := (-1)^{f(x)} = \begin{cases} -1 & \text{if } f(x)=0 \\ 1 & \text{if } f(x)=1 \end{cases}$.

$\rightarrow \Pr_{x,y} [(-1)^{f(x)} \cdot (-1)^{f(y)} \cdot (-1)^{-f(x+y)} = 1] = \mathbb{E}_{x,y} \left[\frac{1 + F(x)F(y)F(x+y)}{2} \right]$.

$\because$ Observe that $\mathbb{1}\{a=0\} = \frac{1+(-1)^a}{2}$. $\mathbb{1}\{f(x) + f(y) - f(x+y) = 0\} = \frac{1 + F(x)F(y)F(x+y)}{2}$.

$\rightarrow \frac{1}{2} + \frac{1}{2} \mathbb{E}_{x,y} [F(x)F(y)F(x+y)] = \frac{1}{2} + \frac{1}{2} \mathbb{E}_{x,y} \left[\left(\sum_s \hat{F}_s \chi_s(x) \right) \left(\sum_\tau \hat{F}_\tau \chi_\tau(y) \right) \left(\sum_u \hat{F}_u \chi_u(x+y) \right) \right]$

$= \frac{1}{2} + \frac{1}{2} \sum_{s,\tau,u} \hat{F}_s \hat{F}_\tau \hat{F}_u \mathbb{E}_{x,y} [\chi_s(x) \chi_\tau(y) \chi_u(x+y)] = \mathbb{E}_{x,y} [\chi_s(x) \chi_\tau(y) \chi_u(x) \chi_u(y)]$

$= \mathbb{E}_x [\chi_s(x) \chi_u(x)] \mathbb{E}_y [\chi_\tau(y) \chi_u(y)] = \langle \chi_s, \chi_u \rangle \langle \chi_\tau, \chi_u \rangle = \mathbb{1}\{s=\tau=u\}$.

$\rightarrow \frac{1}{2} + \frac{1}{2} \sum_{s,\tau,u} \hat{F}_s \hat{F}_\tau \hat{F}_u \mathbb{1}\{s=\tau=u\} = \frac{1}{2} + \frac{1}{2} \sum_s \hat{F}_s^3$.

$\Rightarrow$ If $\frac{1}{2} + \frac{1}{2} \sum_s \hat{F}_s^3 \geq \frac{1}{2} + \delta$, then $\sum_s \hat{F}_s^3 \geq 2\delta$. We know that $\sum_s \hat{F}_s^2 = 1$.

$2\delta \leq \sum_s \hat{F}_s^3 \leq \sum_s \hat{F}_s^2 \cdot \hat{F}_s \leq \sum_s \hat{F}_s^2 \cdot (\max_\tau \{\hat{F}_\tau\}) \leq \max_\tau \{\hat{F}_\tau\}$.

$$F_T(x) = E_x[f(x) X_T(x)] = E_x[(-1)^{f(x)} \cdot (-1)^{\sum_{i \in T} x_i}] = 2 P_x[f(x) = \sum_{i \in T} x_i] - 1.$$

⇒ maximum alignment is bounded by below! //

Recall: MAX 3-SAT is hard to approximate better than $1 - 10^{-6}$.

In general, $NP \rightarrow 3SAT \emptyset \Rightarrow$ if NP is unsat., $gap(\emptyset) \geq 10^{-6}$.

There is also a reduction of $3SAT \emptyset \rightarrow 2-CSP \ G \Rightarrow gap(\emptyset) \propto gap(G)$

↳ How would we increase the gap?



Idea: Parallel Repetition. Let $H^{(k)} := (U \cup V, E)$ where $U := k$ -tuples of clauses from $\emptyset$, $V := k$ -tuples of variables from $\emptyset$. $(C_{i_1, \dots, i_k} \leftrightarrow (x_{i_1}, \dots, x_{i_k}))$

iff $(x_{i_1} \in C_{i_1}) \wedge (x_{i_2} \in C_{i_2}) \dots \wedge (x_{i_k} \in C_{i_k})$. Let an assignment A :

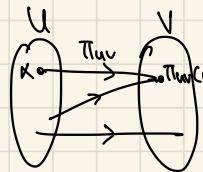
$$U \rightarrow \{0, 1\}^{3k}$$

$$V \rightarrow \{0, 1\}^k.$$

→ stated w/o proof here.

Theorem) $val(\emptyset) = 1 \Leftrightarrow val(H^{(k)}) = 1$. $val(\emptyset) \leq 1 - \epsilon \Leftrightarrow val(H^{(k)}) = e^{-\Omega(k)}$.

Label Cover (2-CSP): $H := (\overline{U \cup V}, E, [R], \{\pi_{uv}: [R] \rightarrow [R] \mid (u, v) \in E\})$.
 $\overline{U \cup V} = \emptyset$ → alphabet

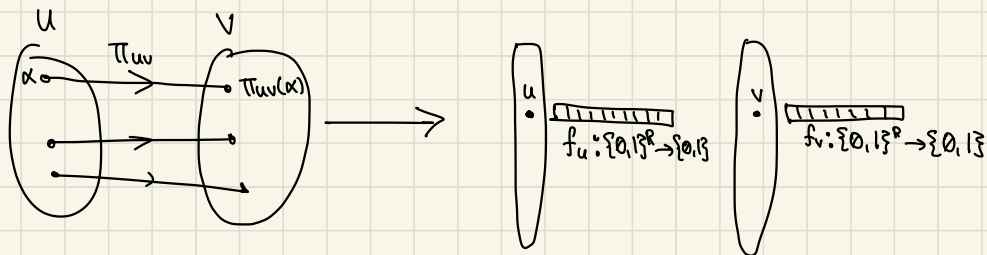


An assignment $A: U \cup V \rightarrow [R]$ satisfies an edge (u, v) if $\pi_{uv}(A(u)) = A(v)$.

↳ reduction $NP \rightarrow$ Label Cover s.t. $val(NP) < 1 \Rightarrow val(H) < \frac{1}{|R|^{p.1}}$.

i.e. $x+y+z = \{0, 1\}$

Proof Idea: Label Cover $\rightarrow$ 3-LIN (lin. eq. mod 2 w/ 3 variables).



If $A(u) = j \in \{1, \dots, R\}$, we want $f_u(x) = x_j$ (dictator function). Also, $A(v) = l \in \{1, \dots, R\}$, we want $f_v(y) = y_l$. This the most redundant code.

Consider an inefficient test: Test linearity on f_u & f_v . Test consistency to the map by π_{uv} , i.e. if $f_u(x) = x_j$, then $f_v(y) = y_{\pi_{uv}(j)}$, or, if $f_u(x) \equiv j$ -th dictator $\Rightarrow f_v(y) \equiv \pi_{uv}(j)$ -th dictator.

For a random x , check $f_u(\pi_{uv} \cdot x) = f_v(x)$ where $(\pi_{uv} \cdot x)_j = x_{\pi_{uv}(j)}$. (a "pullback")

$\hookrightarrow$ But this only checks for linearity.

$$\pi_{uv} \cdot x \begin{bmatrix} 0 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ x \\ x \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix} x$$

Noise Test: Pick $x \in \{0,1\}^n$. Let $\tilde{x} := \epsilon$ -noisy x , $\tilde{x}_i = \begin{cases} x_i & \text{w.p. } 1-\epsilon \\ 0/1 & \text{w.p. } \epsilon \end{cases}$.

Test if $f_u(x) = f_u(\tilde{x})$. Observe that for a dictator, $f_u(x) = x_i$,

$\Pr[f_u(x) = f_u(\tilde{x})] = 1 - \epsilon$. For linear functions not a dictator, say, a parity function $f_u(x) = \sum_{i=1}^n x_i \pmod{2}$, $\Pr[f_u(x) = f_u(\tilde{x})] = \frac{1}{2} + \frac{(1-\epsilon)^d}{2}$.

$\Rightarrow$ Dictators are robust, others are not.

* Hastad's 3 bit PCP wraps all of these tests into one 3-bit query!

1) Pick $(u, v) \in E$ u.a.r. $f_u, f_v: \{0, 1\}^R \rightarrow \{0, 1\}$.

2) Pick $x, y \in \{0, 1\}^R$ u.a.r.

3) Test if $\underbrace{f_v(x) = f_u(\pi_{uv} \circ x + y)}_{\text{consistency}} - \underbrace{f_u(y)}_{\text{linearity}} \stackrel{\text{small noise}}{\rightarrow} y + \mu$ where $\mu_i := \begin{cases} 0 & \text{w.p. } 1-\epsilon \\ 1 & \text{w.p. } \epsilon \end{cases}$
 $\rightarrow$ noise

Caveat: $\emptyset(x)$ is a solution, so we insist that $f_u(x) = 1 - f_u(-x)$, same for v .

$\Rightarrow$ The equation is a linear equation of 3 variables! $\rightarrow$ 3LIN

Recall that the goal is to get completeness $(1-\epsilon)$ and soundness $(\frac{1}{2} + o(1))$.

$\hookrightarrow$ Completeness naturally follows from the true dictator, which is robust.

Soundness Analysis: We shall prove that $\text{Val}(3\text{LIN}) \geq \frac{1}{2} + \delta \Rightarrow \text{Val}(\text{Label Cover}) \geq \delta'$.

Proof: $F_v(x) = F_u(\pi \cdot x \oplus y \oplus \mu) - F_u(y) \Leftrightarrow F_v(x) \oplus F_u(\pi \cdot x \oplus y \oplus \mu) \oplus F_u(y) = 0$.

Define $f_u(x) = (-1)^{F_u(x)}$. Then, $\Leftrightarrow \frac{1 + f_v(x) \cdot f_u(\pi \cdot x \oplus y \oplus \mu) \cdot f_u(y)}{2}$.

$\Pr_{u,v,x,y,\mu} [F_v(x) = F_u(\pi \cdot x \oplus y \oplus \mu) - F_u(y)] = \frac{1}{2} + \frac{1}{2} \mathbb{E}_{u,v,x,y,\mu} [f_u(\pi \cdot x \oplus y \oplus \mu) \cdot f_u(y) \cdot f_v(x)] \geq \frac{1}{2} + \delta$.

Let $A := f_u, B := f_v$. Then, $\mathbb{E}_{u,v,x,y,\mu} [A(\pi \cdot x \oplus y \oplus \mu) A(y) \cdot B(x)] \geq 2\delta$. Expanding,

$$\begin{aligned} & \mathbb{E}_{x,y,\mu} \left[\left(\sum_s \hat{A}_s \chi_s(\pi \cdot x \oplus y \oplus \mu) \right) \left(\sum_\tau \hat{A}_\tau \chi_\tau(y) \right) \left(\sum_u \hat{B}_u \chi_u(x) \right) \right] \\ &= \sum_{s,\tau,u} \hat{A}_s \hat{A}_\tau \hat{B}_u \mathbb{E}_{x,y,\mu} [\chi_s(\pi \cdot x) \chi_s(y) \chi_s(\mu) \chi_\tau(y) \chi_u(x)] \\ &= \sum_{s,\tau,u} \hat{A}_s \hat{A}_\tau \hat{B}_u \underbrace{\mathbb{E}_x [\chi_s(\pi \cdot x) \chi_u(x)]}_{\hookrightarrow ?^*} \underbrace{\mathbb{E}_y [\chi_\tau(y) \chi_s(y)]}_{\hookrightarrow \mathbb{1}\{S=T\}} \underbrace{\mathbb{E}_\mu [\chi_s(\mu)]}_{\hookrightarrow \prod_{i \in S} \mathbb{E}[\chi_i(\mu)] = (-2\epsilon)^{|S|}} \end{aligned}$$

Lemma) $\chi_s(\pi \cdot x) = \chi_{\pi_2(s)}(x)$ where $\pi_2(s) := \{j \mid j \text{ appears odd \# of times in } \pi(s)\}$

Proof: $S \subseteq \{1, \dots, R\}$. $\pi(S)$ is a multiset $\subseteq \{1, \dots, R\}$. $\chi_S(\pi \cdot x) = \prod_{i \in S} \chi_i(\pi \cdot x)$

$$= \prod_{i \in S} \chi_{\pi(i)}(x) = \prod_{\substack{i \text{ pulled odd} \\ i \text{ pulled even}}} \chi_{\pi(i)}(x) \cdot \prod_{\substack{i \text{ pulled odd} \\ i \text{ pulled even}}} \chi_{\pi(i)}(x) = \chi_{\pi_2(S)}(x). //$$

$$\rightarrow^* \mathbb{E}_x [\chi_S(\pi \cdot x) \chi_u(x)] = \mathbb{E}_x [\chi_{\pi_2(S)}(x) \chi_u(x)] = \mathbb{1}_{\{\pi_2(S) = u\}}.$$

$\Rightarrow$ Simplifies to $\sum_S \hat{A}_S^2 \hat{B}_{\pi_2(S)}^2 (1-2\epsilon)^{|S|} > 2\delta$. Now, recall that by Parseval's Identity, $\sum_S \hat{A}_S^2 = 1$. Sample some $S \sim \text{w.p. } \hat{A}_S^2 \Rightarrow S \subseteq [R]$.

Decoding Procedure: Pick $l \in \mathbb{N}$.

1) For each vertex u , sample $S_u \sim (\hat{f}_{u, S_u})^2 \Rightarrow S_u \subseteq [R]$, $S_v \sim (\hat{f}_{v, S_v})^2$, where $|S_u|, |S_v| < l$ (only prefer small subsets).

2) Assign $A_{uv} \leftarrow$ random label from S_u

$$\Rightarrow \mathbb{E}_{u,v} \left[\sum_S \hat{A}_S^2 \hat{B}_{\pi_2(S)}^2 (1-2\epsilon)^{|S|} \right] \leq \mathbb{E}_{u,v} \left[\sum_S \hat{A}_S^2 \right]^{1/2} \mathbb{E}_{u,v} \left[\sum_S \hat{A}_S^2 \hat{B}_{\pi_2(S)}^2 (1-2\epsilon)^{2|S|} \right]^{1/2} \rightarrow \geq \delta^2$$

$$\rightarrow \mathbb{E}_{u,v} \left[\sum_{S: |S| \leq l} \hat{A}_S^2 \hat{B}_{\pi_2(S)}^2 \right] \geq \delta^2/10 \quad (l \leftarrow \frac{(0 \log(Y_\delta))}{\epsilon})$$

$\rightarrow$ For a random edge, $\Pr[\pi_2(S_u) = S_v] \geq \delta^2/10$.

$\rightarrow \Pr[\pi_{uv}(A_{uv}) = A(v)] \geq \delta^2/10 \cdot 1/l^2 = \delta'(8, \epsilon). //$

Unique Games

Recall that 3LIN_p is a system of lineqs mod $\mathbb{Z}_p$ with 3 variables each.

$\hookrightarrow$ It is NP-Hard to distinguish $\text{Val}(3\text{LIN}_p) \geq (1-\epsilon) \leftrightarrow \text{Val}(3\text{LIN}_p) < 1/p + \epsilon$

What about 2LIN_p? This seems easier than 3LIN_p.

Conj) Unique Games Conjecture: $\forall \epsilon, \exists p$ s.t. it is NP-Hard to distinguish $\text{Val}(2\text{LIN}_p) \simeq (1 - \epsilon \leftrightarrow \text{Val}(2\text{LIN}_p) < \epsilon)$. [03' Khot]

Def) Unique Games: a generalization of 2LIN_p, which is Label Cover where all $\pi_{uv}: [R] \rightarrow [R]$ are bijections.

Remark: $\exists$ algorithm A s.t. on input UG instance of value $(1 - \epsilon)$, A outputs an assignment with value $(1/p^{\epsilon/2-\epsilon})$. [CMM 06']

Remark 2: UG on expanders is easy [09']

Remark 3: Subexponential time algorithm for UG: runtime 2^{n^ϵ} . [11']

Remark 4: deg 8 SoS SDP relaxation solves "some important UG instances" [12']

[19'] 2-to-1 problem is NP-Hard!

Hardness of MAXCUT

"Assuming Unique Games Conjecture, it is NP-Hard to beat 0.878 factor."

Recall that $\text{MAXCUT}(G) = \max_{x \in \{\pm 1\}^n} \left\{ \frac{1}{|E|} \sum_{(i,j) \in E} (x_i - x_j)^2 \right\}$. The SDP assigns $v_i \in \mathbb{R}^n \forall i$ where $\|v_i\|^2 = 1$ s.t. every vertex gets embedded on a unit sphere that maximizes distances between connected vertices. Then a random

cut through the origin determines the rounded cut. $\rightarrow 0.878$ factor.

$\hookrightarrow$ Can we specify a worst case instance where 0.878 is tight?

Consider the "^{(S _{α}})Sphere Graph": vertices are all points on S^n , unit sphere on $\mathbb{R}^n$.

Edge set is $\{x, y\} \in S^n \mid \|x - y\| = \alpha\}$. What is the $\text{SDPVal}(S_\alpha)$?

All points x are naturally mapped to $\vec{x} \in \mathbb{R}^n \Rightarrow \text{SDPVal}(G) = \text{average squared edge length} = \frac{\alpha^2}{4}$. $\text{OPTCut}(S_\alpha) = \text{Half-Space Cut (by Borell)}$. Then,

$\text{OPTval}(S_\alpha) = \Pr_{x, y}[\text{half space } H \text{ cuts } x, y] = \Pr_H[H \text{ cuts } x, y \mid \|x - y\| = \alpha] = \phi(\alpha)$.

$$\Rightarrow \frac{\text{OPTval}(S_\alpha)}{\text{SDPval}(S_\alpha)} = 0.878.$$

Dictatorship Testing Gadget: an instance of ^(H)MAXCUT where its vertices are hypercubes, $\{\pm 1\}^R$. ^{$\rightarrow$ const.}A cut is a function $F: \{\pm 1\}^R \rightarrow \{\pm 1\}$. We want:

1) Completeness: If $F(x) = x_i$, then $\text{val}_H(F) = \mathbb{E}_{x \in H} [1\{F(x) \neq F(y)\}] = \frac{\alpha^2}{4}$.

2) Soundness: If F is "far from" all dictators, $\text{val}_H(F) \leq \text{OPT}(S_\alpha)$. $\text{SDP}(S_\alpha)$

$\hookrightarrow$ What do we mean by "far from"? $\rightarrow$ Influences: Given $F: \{\pm 1\}^R \rightarrow \{\pm 1\}$, the influence of the i -th coordinate is $\Pr_{x \sim \{\pm 1\}^R} [F(x) \neq F(x \oplus e_i)]$. ^(flipping i -th bit)

ex) Suppose $F(x) = x_i$. Then $\text{Inf}_i(F) = 1\{i = i\}$.

$\rightarrow \text{Inf}_i(F) := \mathbb{E}_x \left[\frac{(F(x) - F(x \oplus e_i))^2}{4} \right] = \sum_{s \ni i} \hat{F}_s^2$ by Fourier Expansion.

* Inf is well defined for non-boolean functions, too: $F(x) = \mathbb{E}_{x_i} [\text{Var}_{x_i}(F(x))]$.

⇒ Being "far from" a dictator is then having $\forall i, \text{Inf}_i(F) < \tau = o(1)$.

ex) $\text{Maj}(X)$ is far from dictator since $\text{Inf}_i(\text{Maj}) = O(1) \cdot \frac{1}{\sqrt{R}}$.

Edge set of H is $\{(x,y) \in V \mid \text{Ham}(x,y) = \frac{\alpha^2}{4} \cdot R\}$. We can sample edges as follows: pick $x \in \{\pm 1\}^R$, and construct y s.t. $y_i = \begin{cases} x_i & \text{w.p. } 1-p \\ -x_i & \text{w.p. } p \end{cases}$ where $p = 1 - \frac{\alpha^2}{4}$.

Then, we can construct a weighted graph s.t. $w(x,y) = \Pr[(x,y) \text{ is sampled}]$.

Lemma) If F is a dictator, then $\text{Val}_H(F) = \text{SDP}(S_x)^{(\alpha^2/4)}$. [Completeness]

Proof: WLOG, let $F(x) = x_1$. $\text{Val}_H(F) = \Pr_{(x,y) \in E_H} [F(x) \neq F(y)] = \Pr_{(x,y)} [x_1 \neq y_1] = \frac{\alpha^2}{4} = \text{SDP}(S_x)$ by construction.

Soundness: Suppose $\max_i \text{Inf}_i(F) < \tau = o(1)$. We want $\Pr_{(x,y)} [F(x) \neq F(y)] \leq \text{OPT}(S_x) \rightarrow$ (from "Sphere Graph"). Observe that we can view y as a noisy copy of x . Then $\Pr_{(x,y)} [F(x) \neq F(y)]$ is interpreted as noise sensitivity.

Def) Noise Stability: $\Pr[F(x) = F(y) \mid y = \text{Noise}_p(x)]$. $E[F] = 0$ (balanced).

→ Dictators are the most noise stable functions of p !

Theorem) $\text{Maj}(X)$ is the most stable out of functions far from dictators, where $\text{NS}_p(F) \leq \text{NS}_p(\text{Maj}) + \epsilon(\tau)$.

* Recall Gaussian, $N(0,1) \in \mathbb{R}$. $N(0,1)^R \leftarrow (g_1, \dots, g_R)$ each of $\mu_i = 0, \sigma_i^2 = 1$.

$\vec{g} \sim N(0, 1)^R$ gives a distribution on $\mathbb{R}^R$. Then $\|\vec{g}\| \simeq \sqrt{R}$, i.e. it is spherically symmetric and almost behaves like a unit vector. Now imagine $(g_i, h_i) \leftarrow N((0, 0), [\frac{1}{2}, \frac{2\epsilon-1}{2}])$ s.t. $E[g_i h_i] = \frac{2\epsilon-1}{2}$. With such correlation, we can construct $\vec{g} \& \vec{h}$ s.t. they have a certain distance apart.

* CLT says that for $F(x) = \frac{1}{\sqrt{R}} \sum_{i=1}^R x_i$, fix any "nice" distribution D over $\mathbb{R}$ where $E_{x \sim D}[x] = 0$, $\text{Var}(x) = 1$. Then $F(x) | x \sim D^R \xrightarrow{R \rightarrow \infty} F(g) | g \sim N(0, 1)^R$.
 $\rightarrow$ fourth moments are bounded by second

Theorem) Invariance Principle: F is a polynomial of $(x_1, \dots, x_n)$ of degree D and $\max_i \text{Inf}_i(F) < \tau$. Then $F(x) | x \sim D^R \rightarrow F(g) | g \sim N(0, 1)^R + O_\tau(1)$.

Proof Scheme for Soundness: We have H (hypercube) and S_x (sphere graph).

We have $F: \{\pm 1\}^R \rightarrow \{\pm 1\}$ s.t. $\max_i \text{Inf}_i(F) < \tau$ (far from dictators)

By Fourier analysis, F is a polynomial. Then $\Pr_{x \in \mathcal{F}^H} [F(x) \neq F(g)] = \Pr_{g \in \mathcal{F}^H} [F(g) \neq F(h)]$.
 $\mathcal{F}^H \xrightarrow{x} \text{booleans}$ $\mathcal{F}^H \xrightarrow{g} N(0, 1)$

By Invariance Principle, cut ratio in F is preserved to S_x , i.e. $\text{Val}_H(F) \simeq \text{Val}_{S_x}(F)$.
 $\leq O(\tau^{1/D})$

Invariance Principle (Formally): Let $x_1, \dots, x_n \stackrel{\text{unif}}{\sim} \{\pm 1\}$, $g_1, \dots, g_n \sim N(0, 1)$. Let

$P(z_1, \dots, z_n)$ be a polynomial of degree $\leq D$ and $\forall i, \text{Inf}_i(P) = \sum_{S \ni i} p_S^2 < \tau$.

Fix any function $\psi: \mathbb{R} \rightarrow \mathbb{R}$ where $\|\psi^{(3)}\| < B$. Then $E[\psi(P(x_1, \dots, x_n))] \simeq$

$E[\psi(P(g_1, \dots, g_n))] + \text{error}(D, \tau)$ where $\text{error}(D, \tau) \rightarrow 0$ as $\tau \rightarrow 0$.

Theorem) Under UGC, it is NP-Hard to approximate MAXCUT better than α .

Proof Idea: Reduce UGC $\rightarrow$ MAXCUT via dictatorship test. (proof omitted)

Construction of Dictatorship Test: Fix $G(V, E)$, an instance of MAXCUT. $\nearrow |V|=n$

Fix any k solutions $x_1, \dots, x_k \in \{0, 1\}^n$ where $\forall x_i, \text{Val}_G(x_i) \geq C$. Let the dictatorship testing graph be H_G . Column wise merge $x_1, \dots, x_k$ to get n k -tuples $X^{(1)}, \dots, X^{(n)}$. Take $V(H_G) := \{0, 1\}^k$, and $\forall i, j \in G \Rightarrow (X^{(i)}, X^{(j)}) \in H_G$. Suppose $f(z) = z_i$ for some $z \in \{0, 1\}^k$. Then $\text{Val}_{H_G}(f) = \text{Val}_G(x_i)$ since we only observe one specific row of each column. By assumption, $\text{Val}_G(x_i) \geq C$. (Completeness) Now suppose f is far from dictator.

What is the "best" dictatorship test (i.e. what is the smallest α)? $\nearrow \alpha_{\text{MAXCUT}}$

$\rightarrow$ Dictatorship test with $\frac{\text{soundness}}{\text{completeness}} < \alpha$.

$\Rightarrow \exists f: \{0, 1\}^k \rightarrow \{0, 1\}$ s.t. it is far from dictator, and $\forall$ graph $G \exists \forall x_1, \dots, x_k \in \{0, 1\}^n$ s.t. $\text{Val}_G(x_i) \geq C, \text{Val}_G(f(x_1, \dots, x_k)) \geq \alpha \cdot C$. (approximate polymorphism)

Def) α -Approximate Polymorphism: (distribution of) functions $F: \{0, 1\}^k \rightarrow \{0, 1\}$ s.t. $\forall G, \forall x_1, \dots, x_k$ where $\text{Val}_G(x_i) \geq C, E[\text{Val}_G(F(x_1, \dots, x_k))] \geq \alpha \cdot C$. $\nearrow$ pointwise eval

$\hookrightarrow$ Dictators are 1-approximate polymorphisms but not interesting.

→ $\alpha_{\text{MAXCUT}} = \max F$ far from dictators but possible α -approx. poly.

Question: α -Approx. Poly. for MAXCUT $\Rightarrow$ α -Approx. Algorithm for MAXCUT?

→ for some $k \in \mathbb{N}$, say 10^6 , $\exists$ function $F: \{\pm 1\}^k \rightarrow \{\pm 1\}$ far from dictators.

Say we have $G(V, E)$, $|V| = n$. If we have $x_1, \dots, x_k \in \{\pm 1\}^n$, and $\text{val}_G(x_i) \geq c$.

Applying $F(x_1, \dots, x_k)$ gives $\text{val}_G(F(x_1, \dots, x_k)) \geq \alpha \cdot c$. But we don't have x_i s.

→ Solve SDP for MAXCUT(G) to get $v^{(1)}, \dots, v^{(n)} \in \mathbb{R}^n$. Pick $z \in N(0, 1)^n$ and apply $v^{(1)} \cdot z, v^{(2)} \cdot z, \dots, v^{(n)} \cdot z =: g$. Then $E[(v^{(1)} \cdot z) \cdot (v^{(2)} \cdot z)] = v^{(1)} \cdot v^{(2)}$.

Now, use $g_1, \dots, g_k$ in the place of $x_1, \dots, x_k$. Apply $F(g_1, \dots, g_k)$.

→ Since F is far from dictator, it is low influence, the invariance principle says that $E_g[\text{val}_G(F(g_1, \dots, g_k))] \geq \alpha \cdot c$.

$\Rightarrow$ Generally, an α -approx. poly. gives an α -approx. algorithm.

Theorem) Under UGC, $\exists$ α -approx. poly. $\Leftrightarrow \exists$ α -dictatorship tests

$\Rightarrow$ MAXCUT is hard to approximate to α .

Upshot: Polymorphisms "determine" the complexity of a CSP. This extends to decision and approximation problems.

Counting # of solutions? $\in \#P$. Which counting problems are in FP (poly time solvable), and which are in $\#P$ -Complete?

↳ A counting CSP $\in FP$ iff it admits a Maltzer Polymorphisms, where $f(a,b,b) = f(b,b,a) = a$ (such as for 3LIN, $f(x,y,z) = x-y+z$).

Else, it is in $\#P$ -Hard.

Two Lines of Work (related to polymorphisms):

1) Approximation under Perfect Completeness: given a fully satisfiable instance, approximate the value. [KMB] $\rightarrow$ (to beat random)

↳ If 3LIN is $(1-\epsilon)$ satisfiable, the problem is hard, but if it is satisfiable, we can just use Gaussian Elimination!

↳ Betweenness CSP: For $P_1, \dots, P_n$, find a permutation π subject to constraints of the form $\pi(p_i) < \pi(p_j) < \pi(p_k)$ $\nearrow$ not flipped. Completeness gives $\alpha=1/2$ instead of $1/3$!

2) Promise CSPs: ex) Given a 3-Colorable graph G , color it using as few colors as possible $\rightarrow$ $\exists$ SDP-based algorithm to get a $n^{0.19\dots}$ coloring. Also, it is NP-Hard to get a 6-coloring.

One emerging topic: Quantum CSPs (analog of PCP in quantum?)